### Programming in CUDA: the Essentials, Part 1

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## Evolution of Graphics Hardware Towards Programmability

- As graphics accelerators became more powerful, an increasing fraction of the graphics processing pipeline was implemented in hardware
- For performance reasons, this hardware was highly optimized and task-specific
- Over time, with ongoing increases in circuit density and the need for flexibility in lighting and texturing, graphics pipelines gradually incorporated programmability in specific pipeline stages
- Modern graphics accelerators are now complete processors in their own right (thus the new term "GPU"), and are composed of large arrays of programmable processing units



## Origins of Computing on GPUs

- Widespread support for programmable shading led researchers to begin experimenting with the use of GPUs for general purpose computation, "GPGPU"
- Early GPGPU efforts used existing graphics APIs to express computation in terms of drawing
- As expected, expressing general computation problems in terms of triangles and pixels and "drawing the answer" is obfuscating and painful to debug...
- Soon researchers began creating dedicated GPU programming tools, starting with Brook and Sh, and ultimately leading to a variety of commercial tools such as RapidMind, CUDA, OpenCL, and others...



# GPU Computing

- Commodity devices, omnipresent in modern computers (over a **million** sold per **week**)
- Massively parallel hardware, hundreds of processing units, **throughput oriented architecture**
- Standard integer and floating point types supported
- Programming tools allow software to be written in dialects of familiar C/C++ and integrated into legacy software
- GPU algorithms are often multicore friendly due to attention paid to **data locality** and **data-parallel work decomposition**



# Benefits of GPUs vs. Other Parallel Computing Approaches

- Increased compute power per unit volume
- Increased FLOPS/watt power efficiency
- Desktop/laptop computers easily incorporate GPUs, no need to teach nontechnical users how to use a remote cluster or supercomputer
- GPU can be upgraded without new OS license fees, low cost hardware



# What Speedups Can GPUs Achieve?

- Single-GPU speedups of **10x** to **30x** vs. one CPU core are very common
- Best speedups can reach **100x** or more, attained on codes dominated by floating point arithmetic, especially native GPU machine instructions, e.g. expf(), rsqrtf(), ...
- Amdahl's Law can prevent legacy codes from achieving peak speedups with shallow GPU acceleration efforts



### GPU Solution: Time-Averaged Electrostatics

- Thousands of trajectory frames
- 1.5 hour job reduced to 3 min
- GPU Speedup: 25.5x
- Per-node power consumption on NCSA GPU cluster:
  - CPUs-only: 448 Watt-hours
  - CPUs+GPUs: 43 Watt-hours
- Power efficiency gain: 10x





#### GPU Solution: Radial Distribution Function Histogramming

- 4.7 million atoms
- 4-core Intel X5550
   CPU: 15 hours
- 4 NVIDIA C2050 GPUs: **10 minutes**
- Fermi GPUs ~3x faster than GT200 GPUs: larger on-chip shared memory

6

r/A

8

10

6

2

0

(1)<sub>d-q</sub>g





### Science 5: Quantum Chemistry Visualization

- Chemistry is the result of atoms sharing electrons
- Electrons occupy "clouds" in the space around atoms
- Calculations for visualizing these "clouds" are costly: tens to hundreds of seconds on CPUs – noninteractive
- GPUs enable the dynamics of electronic structures to be animated **interactively** for the first time



VMD enables interactive display of QM simulations, e.g. Terachem, GAMESS



Beckman Institute, U. Illinois at Urbana-Champaign

GPU Solution: Computing C<sub>60</sub> Molecular Orbitals



#### Molecular Orbital Inner Loop, Hand-Coded x86 SSE Hard to Read, Isn't It? (And this is the "pretty" version!)

for (shell=0; shell < maxshell; shell++) {</pre>

 $\_m128 Cgto = \_mm\_setzero\_ps();$ 

for (prim=0; prim<num\_prim\_per\_shell[shell\_counter]; prim++) {</pre>

float exponent = -basis\_array[prim\_counter ];

float contract\_coeff = basis\_array[prim\_counter + 1];

\_\_m128 expval = \_mm\_mul\_ps(\_mm\_load\_ps1(&exponent), dist2);

\_\_m128 ctmp = \_mm\_mul\_ps(\_mm\_load\_ps1(&contract\_coeff), exp\_ps(expval));

Cgto = \_mm\_add\_ps(contracted\_gto, ctmp);

prim\_counter += 2;

}

\_\_m128 tshell = \_mm\_setzero\_ps();
switch (shell\_types[shell\_counter]) {
 case S\_SHELL:

Writing SSE kernels for CPUs requires assembly language, compiler intrinsics, various libraries, or a really smart autovectorizing compiler **and lots of luck...** 

value = \_mm\_add\_ps(value, \_mm\_mul\_ps(\_mm\_load\_ps1(&wave\_f[ifunc++]), Cgto)); break; case P\_SHELL:

tshell = \_mm\_add\_ps(tshell, \_mm\_mul\_ps(\_mm\_load\_ps1(&wave\_f[ifunc++]), xdist)); tshell = \_mm\_add\_ps(tshell, \_mm\_mul\_ps(\_mm\_load\_ps1(&wave\_f[ifunc++]), ydist)); tshell = \_mm\_add\_ps(tshell, \_mm\_mul\_ps(\_mm\_load\_ps1(&wave\_f[ifunc++]), zdist)); value = \_mm\_add\_ps(value, \_mm\_mul\_ps(tshell, Cgto)); break;



### **Molecular Orbital Inner Loop in CUDA**

```
for (shell=0; shell < maxshell; shell++) {</pre>
```

```
float contracted_gto = 0.0f;
```

for (prim=0; prim<num\_prim\_per\_shell[shell\_counter]; prim++) {</pre>

float exponent = const\_basis\_array[prim\_counter ];

float contract\_coeff = const\_basis\_array[prim\_counter + 1];

contracted\_gto += contract\_coeff \* exp2f(-exponent\*dist2);

prim\_counter += 2;

float tmpshell=0;

```
switch (const_shell_symmetry[shell_counter]) {
  case S_SHELL:
```

```
value += const_wave_f[ifunc++] * contracted_gto; break;
```

```
case P_SHELL:
```

```
tmpshell += const_wave_f[ifunc++] * xdist;
```

```
tmpshell += const_wave_f[ifunc++] * ydist
```

```
tmpshell += const_wave_f[ifunc++] * zdist;
```

value += tmpshell \* contracted\_gto; break;



Aaaaahhhh....

Data-parallel CUDA kernel looks like normal C code for the most part....



#### Theoretical GB/s

#### Peak Memory Bandwidth Trend



# What Runs on a GPU?

- GPUs run data-parallel programs called "kernels"
- GPUs are managed by a host CPU thread:
  - Create a CUDA context
  - Allocate/deallocate GPU memory
  - Copy data between host and GPU memory
  - Launch GPU kernels
  - Query GPU status
  - Handle runtime errors



# CUDA Stream of Execution

- Host CPU thread launches a CUDA "kernel", a memory copy, etc. on the GPU
- GPU action runs to completion
- Host synchronizes with completed GPU action





### Comparison of CPU and GPU Hardware Architecture

**CPU**: Cache heavy, focused on individual thread performance

Control	ALU	ALU
	ALU	ALU
Cache		
DRAM		

**GPU**: ALU heavy, massively parallel, throughput oriented





# GPU: Throughput-Oriented Hardware Architecture

- GPUs have very small on-chip caches
- Main memory latency (several hundred clock cycles!) is tolerated through hardware multithreading – **overlap memory transfer latency with execution of other work**
- When a GPU thread stalls on a memory operation, the hardware immediately switches context to a ready thread
- Effective latency hiding requires saturating the GPU with lots of work tens of thousands of independent work items



## GPU Memory Systems

- GPU arithmetic rates dwarf memory bandwidth
- For Kepler K20 hardware:
  - ~2 TFLOPS vs. ~250 GB/sec
  - The ratio is roughly 40 FLOPS per memory reference for single-precision floating point
- GPUs include multiple fast on-chip memories to help **narrow the gap**:
  - Registers
  - Constant memory (64KB)
  - Shared memory (48KB / 16KB)
  - Read-only data cache / Texture cache (48KB)



#### GPUs Require ~20,000 Independent Threads for Full Utilization, Latency Hidding



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#### **Streaming Multiprocessor**

#### **64KB** Constant Cache

#### 64 KB L1 Cache / Shared Memory





#### **Streaming Multiprocessor - SMX**

64 KB Constant Cache

64 KB L1 Cache / Shared Memory

48 KB Tex + Read-only Data Cache



16 × Execution block = 192 SP, 64 DP, 32 SFU, 32 LDST

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