VMD: GPU-Accelerated Analysis of Biomolecular and Cellular Simulations

John E. Stone

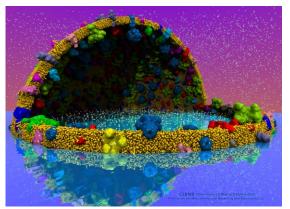
Theoretical and Computational Biophysics Group Beckman Institute for Advanced Science and Technology University of Illinois at Urbana-Champaign http://www.ks.uiuc.edu/Research/vmd/ Cray Analytics Symposium, Friday May 26th, 2017





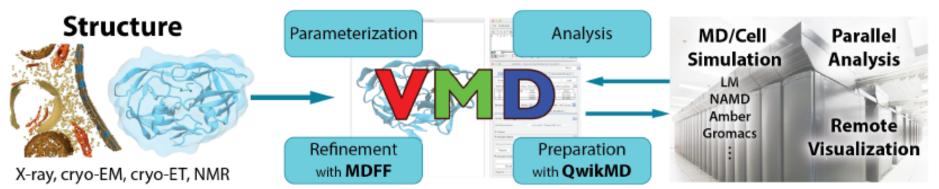
VMD – "Visual Molecular Dynamics"

- Visualization and analysis of:
 - Molecular dynamics simulations
 - Lattice cell simulations
 - Quantum chemistry calculations
 - Sequence information
- User extensible scripting and plugins
- http://www.ks.uiuc.edu/Research/vmd/



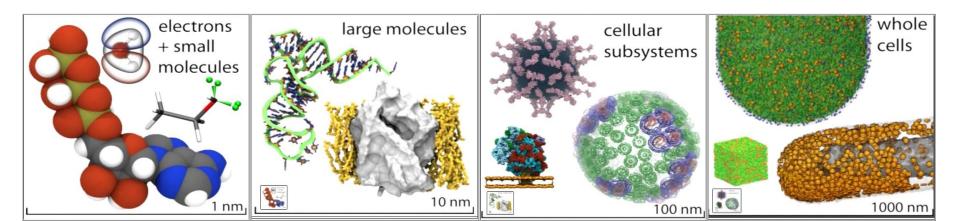
Cell-Scale Modeling





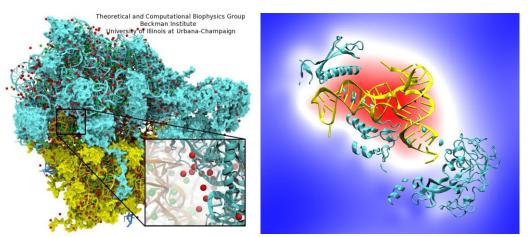
VMD Interoperability Serves Many Communities

- Uniquely interoperable with a broad range of tools:
 - AMBER, CHARMM, CPMD, DL_POLY, GAMESS, GROMACS, HOOMD, LAMMPS, NAMD, and many more ...
- Supports key data types, file formats, and databases
- Incorporates tools for simulation preparation, visualization, and analysis



10 Years of GPU Computing in VMD

- Has stood the test of time
- Modeling, Visualization, Rendering, and Analysis



Accelerating molecular modeling applications with graphics processors. J. Stone, J. Phillips, P. Freddolino, D. Hardy, L. Trabuco, K. Schulten. *J. Comp. Chem.*, 28:2618-2640, 2007.

Blast from the past:

CUDA starting with version 0.7 !!!

Quad core Intel QX6700, three NVIDIA GeForce 8800GTX GPUs, RHEL4 Linux

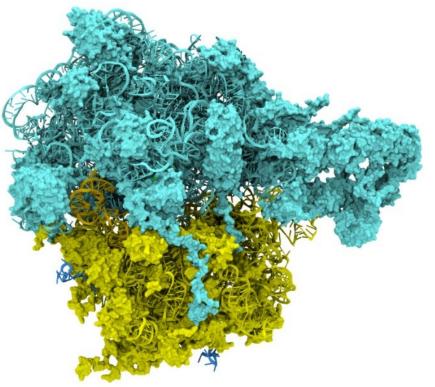


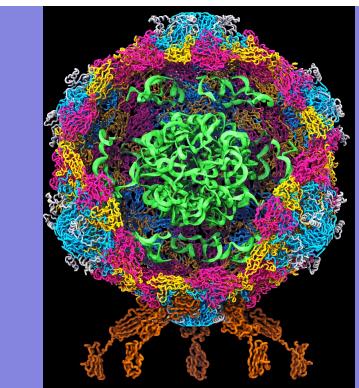
Goal: A Computational Microscope

Study the molecular machines in living cells

Ribosome: target for antibiotics

Poliovirus





VMD Petascale Visualization and Analysis

- Analyze/visualize large trajectories too large to transfer off-site:
 - User-defined parallel analysis operations, data types
 - Parallel rendering, movie making
- Supports GPU-accelerated Cray XK7 nodes for both visualization and analysis:
 - GPU accelerated trajectory analysis w/ CUDA
 - OpenGL and GPU ray tracing for visualization and movie rendering
- Parallel I/O rates up to 275 GB/sec on 8192 Cray XE6 nodes – can read in 231 TB in 15 minutes!

Parallel VMD currently available on:

ORNL Titan, NCSA Blue Waters, Indiana Big Red II, CSCS Piz Daint, and similar systems



NCSA Blue Waters Hybrid Cray XE6 / XK7 22,640 XE6 dual-Opteron CPU nodes 4,224 XK7 nodes w/ Telsa K20X GPUs





Interactive Remote Visualization and Analysis

- Enabled by hardware H.264/H.265 video encode/decode
- Enable visualization and analyses not possible with conventional workstations
- Access data located anywhere in the world

 Same VMD session available to any device
- Linux prototype in-development using NVIDIA Video Codec SDK, easy-to-use
 NvPipe wrapper library

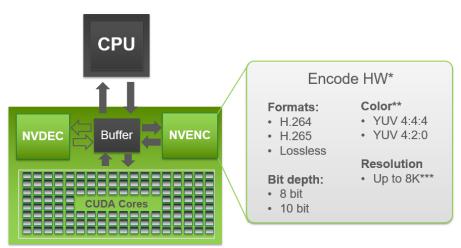




NVIDIA Video CODEC SDK and NvPipe

- GPUs (Kepler-on) include NVENC and NVDEC video codec acceleration hardware
- Independent of GPU compute hardware
- Hardware-accelerated codecs can overlap with interactive rendering, and computation
- NvPipe provides an easy to use API for interactive video streaming, abstracting many low level codec details, ideal for basic remote visualization implementations:

https://github.com/NVIDIA/NvPipe



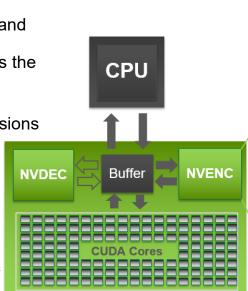




NvPipe

https://github.com/NVIDIA/NvPipe

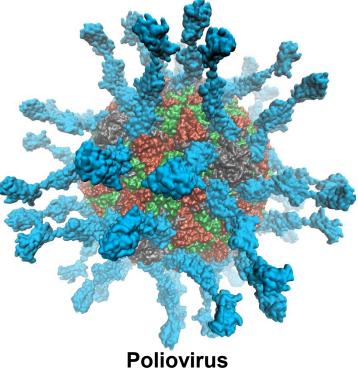
- Simplified API for producing a basic encoder/decoder system.
- Roughly 100 lines of code for basic encode/decode "Hello World" loops with minimal error handling logic
- Encode/decode ends up being simpler than your networking code ©
- Encode loop structure:
 - User selects encoder type, e.g. NVPIPE_H264_NV, and target encoder bitrate parameter
 - User provides uncompressed RGB or RGBA image buffer, image dimensions, and size of the output memory buffer
 - NvPipe compresses the frame using the NVENC hardware encoder, and returns the number of bytes of output written to the output buffer
- Symmetric decode loop structure:
 - Provide decoder with compressed buffer, buffer size in bytes, and image dimensions as input
 - Decoder produces uncompressed output image
- Optionally supports FFMPEG back-ends (but I haven't tried those yet)



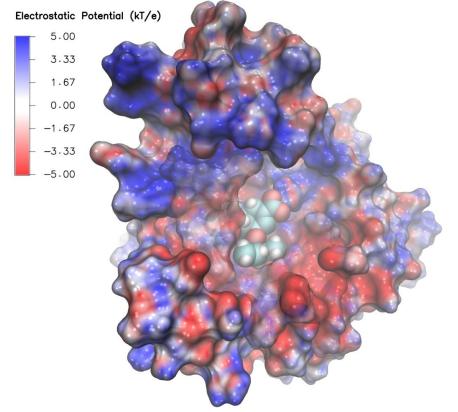


VMD 1.9.3 supports EGL for in-situ and parallel rendering on clouds, clusters, and supercomputers

- Eliminate dependency on windowing systems
- Simplified deployment of parallel VMD builds supporting offscreen rendering
- Maintains 100% of VMD OpenGL shaders and rendering features
- Support high-quality vendorsupported commercial OpenGL implementations in HPC systems that were previously limited to Mesa







Swine Flu A/H1N1 neuraminidase bound to Tamiflu: VMD EGL rendering demonstrating full support for all VMD shaders and OpenGL features, multisample antialiasing, ray cast spheres, 3-D texture mapping, ...





EGL Is Supported Now!

- Cloud+Workstations with most recent NVIDIA drivers
- VMD on HPC systems w/ latest Tesla P100 GPUs:
 - Cray XC50, CSCS Piz Daint, driver 375.39



High Performance Molecular Visualization: In-Situ and Parallel Rendering with EGL. J. E. Stone, P. Messmer, R. Sisneros, and K. Schulten. High Performance Data Analysis and Visualization Workshop, IEEE International Parallel and Distributed Processing Symposium Workshop (IPDPSW), pp. 1014-1023, 2016.







https://www.khronos.org/vulkan/

- In-progress: Vulkan-based rasterization path for VMD
 - Modern API, reduced dependence on extensions for modern functionality
 - Significantly reduced API overheads relative to OpenGL, some other apps have seen ~2x performance gains vs. OpenGL
 - Shaders (e.g. GLSL) compiled to SPIR-V intermediate code
 - Compile-time rather than runtime verification of rendering pipelines
 - Integration with windowing system is handled by Vulkan extensions
 - Multi-GPU rendering wasn't part of Vulkan 1.0 spec, but is in development





Benefits of CS Storm NVLink Peer-to-Peer GPU Communication for VMD

- Rapid peer-to-peer GPU data transfers:
 - Use aggregate GPU memory to collectively cache/share large host-side data
 - Rapid access to large data structures too large to fit entirely in single-GPU memory
 - Bypass host whenever possible, perform nearest-neighbor exchanges for pairwise calculations, e.g. those that arise in algorithms for simulation trajectory clustering
 - Well suited for high-fidelity ray tracing of scenes containing massive amounts of geometry





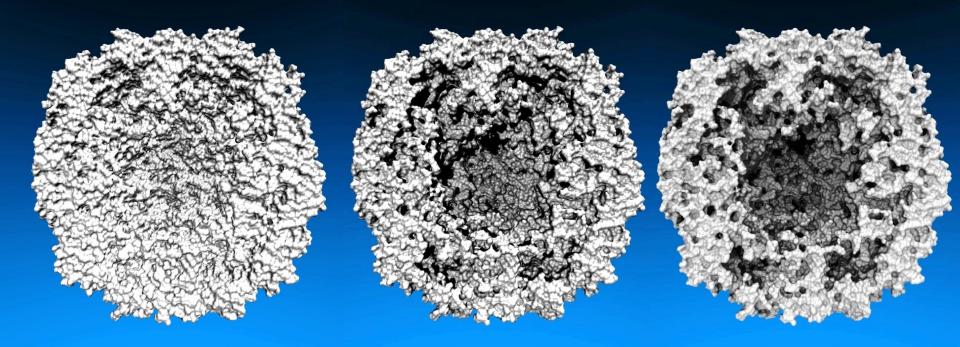
VMD w/ OptiX 4.1

- Interactive RT on laptops, desktops, and cloud
- Large-scale parallel rendering: in situ or post hoc visualization tasks
- Remote RT on NVIDIA VCA clusters
- Stereoscopic panoramic and full-dome projections
- Omnidirectional VR for YouTube, VR HMDs
- Top-end Pascal Tesla GPUs roughly 2x faster than Kepler
- GPU memory sharing via NVLink on Quadro GP100, Tesla P100

GPU-Accelerated Molecular Visualization on Petascale Supercomputing Platforms. J. E. Stone, K. L. Vandivort, and K. Schulten. UltraVis'13, pp. 6:1-6:8, 2013. Visualization of Energy Conversion Processes in a Light Harvesting Organelle at Atomic Detail. M. Sener, et al. SC'14 Visualization and Data Analytics Showcase, 2014. Chemical Visualization of Human Pathogens: the Retroviral Capsids. J. R. Perilla, B.-C. Goh, J. E. Stone, and K. Schulten. SC'15 Visualization and Data Analytics Showcase, 2015. Atomic Detail Visualization of Photosynthetic Membranes with GPU-Accelerated Ray Tracing. J. E. Stone et al., J. Parallel Computing, 55:17-27, 2016. Immersive Molecular Visualization with Omnidirectional Stereoscopic Ray Tracing and Remote Rendering J. E. Stone, W. R. Sherman, and K. HPDAV, IPDPSW, pp. 1048-1057, 2016.

VMD/OptiX GPU Ray Tracing of all-atom Chromatophore w/ lipids.

Lighting Comparison, STMV Capsid Two lights, no Two lights, Ambient occlusion shadows hard shadows, + two lights, 1 shadow ray per light 144 AO rays/hit



Preparation, Visualization, Analysis of All-Atom Cell-Scale Simulations

- Interactive rasterization w/ OpenGL/EGL now, Vulkan in future releases of VMD
- Interactive ray tracing on CPUs and GPUs
- Support for large host memory (TB), up to
 2 billion atoms per "molecule" now
- Parallel analysis, visualization w/ MPI

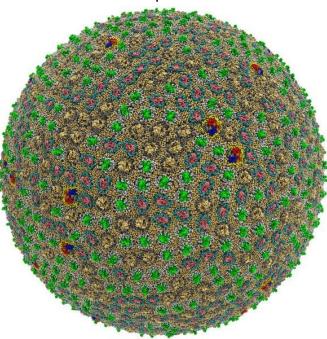
Atomic Detail Visualization of Photosynthetic Membranes with GPU-Accelerated Ray Tracing. J.E. Stone, ..., K. Schulten, J. Parallel Computing, 55:17-27, 2016.

High Performance Molecular Visualization: In-Situ and Parallel Rendering with EGL. J.E. Stone, ..., K. Schulten. IEEE High Performance Data Analysis and Visualization, IPDPSW, pp. 1014-1023, 2016.



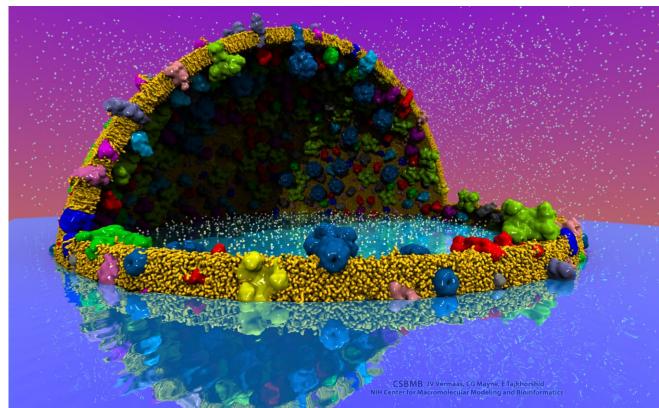
Biomedical Technology Research Center for Macromolecular Modeling Beckman Institute, University of Illinois at Urbana-Champaign - ww

- 200 nm spherical envelope
- Membrane with ~50% occupancy by proteins
- 63M atoms in envelope model



Proto-Cell Rendered with VMD+OptiX

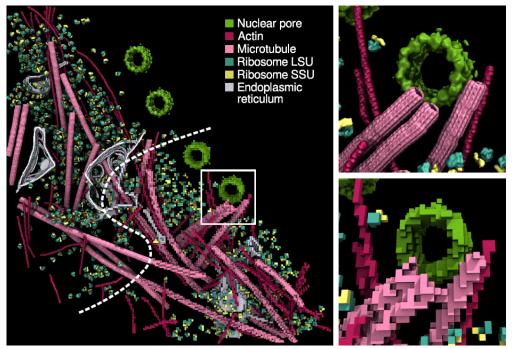
- 113M particles
- 1,397 copies of 14 different membrane proteins
- Preparing for simulations on pre-exascale computers





Interactive Ray Tracing of Cells

- High resolution cellular tomograms, billions of voxels
- Even isosurface or lattice site graphical representations involve ~100M geometric primitives
- 24GB Quadro M6000s used for interactive RT of cellular tomograms of this size
- Latest Quadro GP100 GPUs benefit from OptiX 4.1 support for NVLink and distribution of scene data across multiple GPUs



Earnest, et al. J. Physical Chemistry B, 121(15): 3871-3881, 2017.

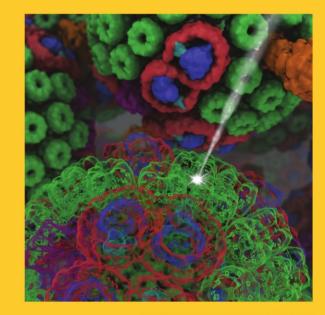


VMD Molecule Instancing: In-Progress Development

- VMD 1.9.4 supports instancing of graphical representations associated with molecules
- Will exploit VBO caching in OpenGL to eliminate host-GPU geometry transfers
- OptiX instancing of geometry buffers to eliminate GPU memory consumption for instances

APRIL 20, 2017 VOLUME 121 NUMBER 15 pubs.acs.org/JPCB





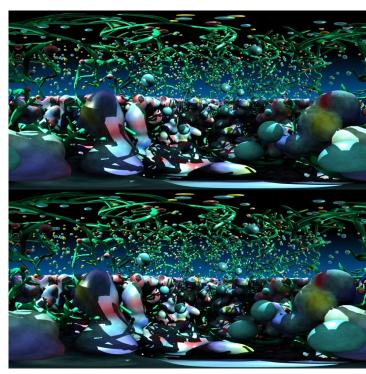
KLAUS SCHULTEN MEMORIAL ISSUE





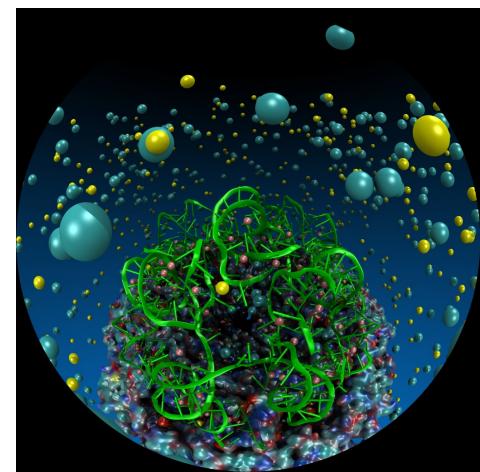
Stereoscopic Panorama Ray Tracing w/ OptiX

- Render 360° images and movies for VR headsets such as Oculus Rift, Google Cardboard
- Ray trace panoramic stereo spheremaps or cubemaps for very high-frame-rate display via OpenGL texturing onto simple geometry
- Stereo requires spherical camera projections poorly suited to rasterization
- Benefits from OptiX multi-GPU rendering and load balancing, VCA remote rendering

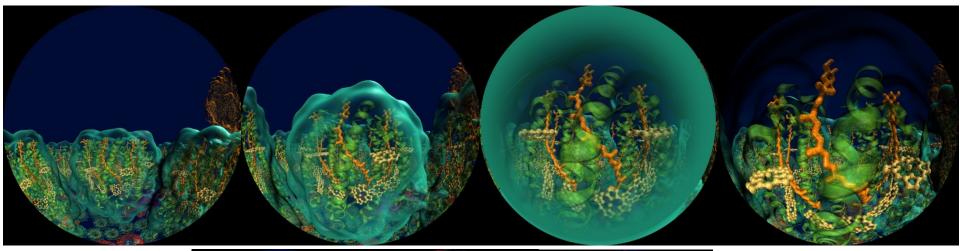


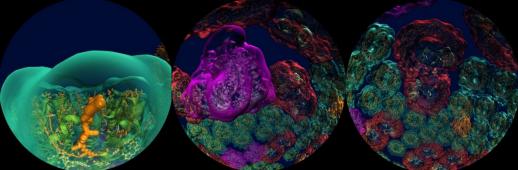
VMD Planetarium Dome Master Camera

- Trivial to implement in OptiX
- 40 lines of CUDA code including antialiasing and handling corner cases for transcendental fctns
- Try implementing this in OpenGL . . . (yuck)
- Stereoscopic cameras and other special purpose projections are similarly easy



CADENS "Birth of Planet Earth" Planetarium Dome Master Test Frames

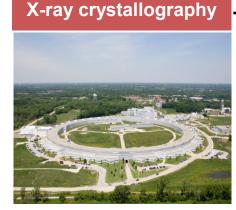








Molecular Dynamics Flexible Fitting (MDFF)



APS at Argonne





Electron microscopy

FEI microscope

ORNL Titan





Molecular dynamics-based refinement and validation for sub-5Å cryoelectron microscopy maps. A. Singharoy, I. Teo, R. McGreevy, J. E. Stone, J. Zhao, and K. Schulten. eLife 2016;10.7554/eLife.16105

Molecular Dynamics Flexible Fitting - Theory

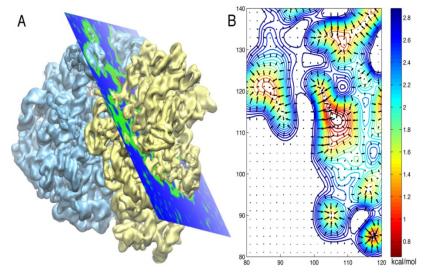
Two terms are added to the MD potential

 $U_{total} = U_{MD} + U_{EM} + U_{SS}$

An external potential derived from the EM map is defined on a grid as

$$U_{EM}(\mathbf{R}) = \sum_{j} w_{j} V_{EM}(\mathbf{r}_{j})$$
$$V_{EM}(\mathbf{r}) = \begin{cases} \xi \left(1 - \frac{\Phi(\mathbf{r}) - \Phi_{thr}}{\Phi_{max} - \Phi_{thr}}\right) & \text{if } \Phi(\mathbf{r}) \ge \Phi_{thr}, \\ \xi & \text{if } \Phi(\mathbf{r}) < \Phi_{thr}. \end{cases}$$

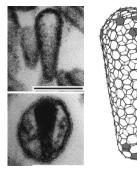
A mass-weighted force is then applied to each atom $\mathbf{f}_{i}^{EM} = -\nabla U_{EM}(\mathbf{R}) = -w_{i}\partial V_{EM}(\mathbf{r}_{i})/\partial r_{i}$

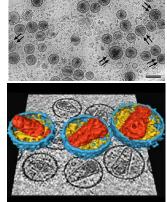




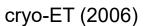
Structural Route to the all-atom HIV-1 Capsid

1st TEM (1999) 1st tomography (2003)

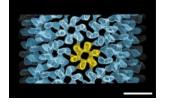




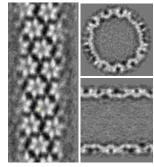
Ganser et al. *Science*, 1999 Briggs et al. *EMBO J*, 2003 Briggs et al. *Structure*, 2006



hexameric tubule

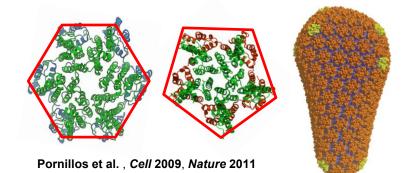


Li et al., Nature, 2000

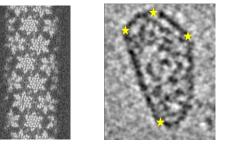


Byeon et al., Cell 2009

Crystal structures of separated hexamer and pentamer



High res. EM of hexameric tubule, tomography of capsid, all-atom model of capsid by MDFF w/ NAMD & VMD, NSF/NCSA Blue Waters computer at Illinois

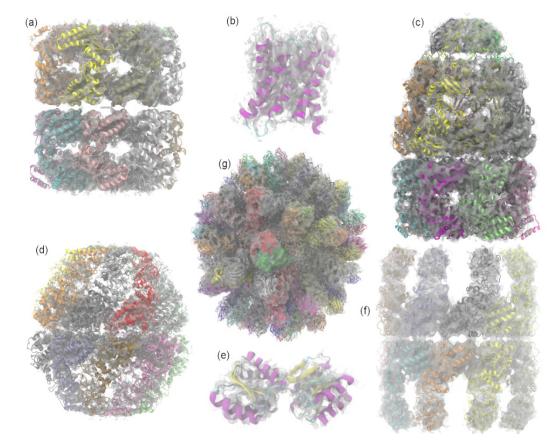




Zhao et al., Nature 497: 643-646 (2013)

Evaluating Quality-of-Fit for Structures Solved by Hybrid Fitting Methods

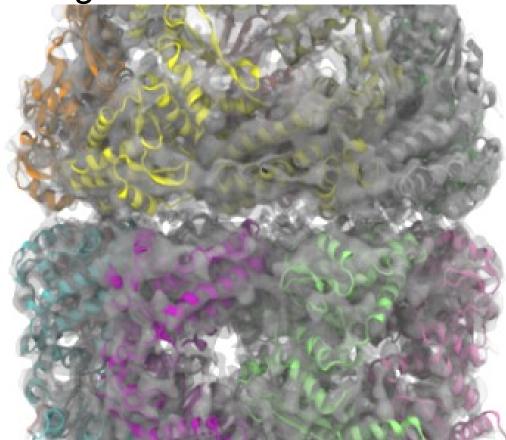
Compute Pearson correlation to evaluate the fit of a reference cryo-EM density map with a simulated density map produced from an all-atom structure.



Evaluating Quality-of-Fit for Structures Solved by Hybrid Fitting Methods

Compute Pearson correlation to evaluate quality-of-fit between a reference cryo-EM density map and a simulated density map produced from an

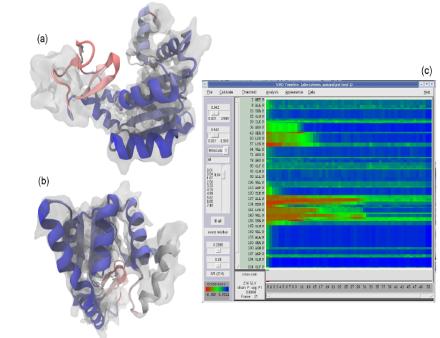
all-atom structure.



GPUs Can Reduce MDFF Trajectory Analysis Runtimes from Hours to Minutes

GPUs enable laptops and desktop workstations to handle tasks that would have previously required a cluster, or a *very long wait*...

GPU-accelerated petascale supercomputers enable analyses that were previously impractical, allowing detailed study of very large structures such as viruses



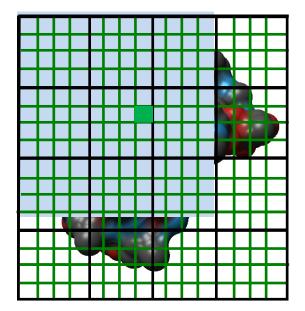
GPU-accelerated MDFF Cross Correlation Timeline Regions with poor fit Regions with good fit

MDFF Density Map Algorithm

- Build spatial acceleration data structures, optimize data for GPU
- Compute 3-D density map:

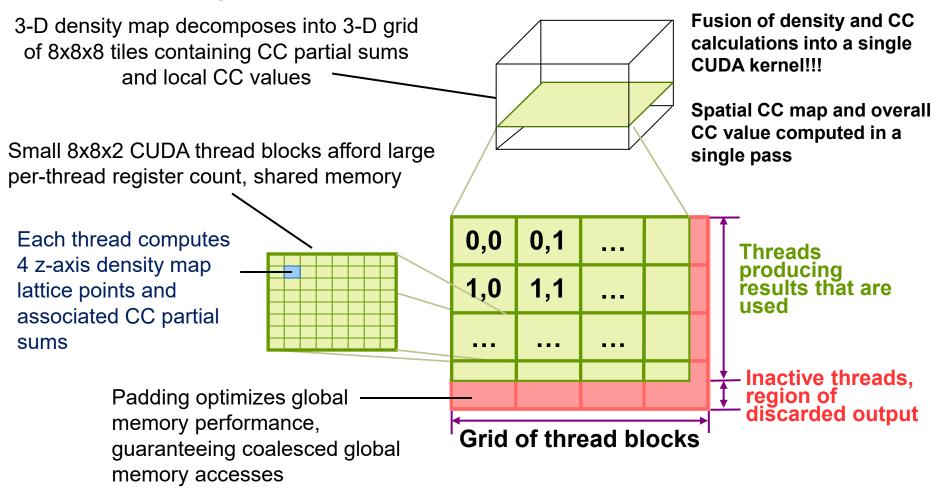
$$\rho(\vec{r}; \vec{r}_1, \vec{r}_2, \dots, \vec{r}_N) = \sum_{i=1}^N e^{\frac{-|\vec{r}-\vec{r}_i|^2}{2\alpha^2}}$$

 Truncated Gaussian and spatial acceleration grid ensure linear time-complexity



3-D density map lattice point and the neighboring spatial acceleration cells it references

Single-Pass MDFF GPU Cross-Correlation



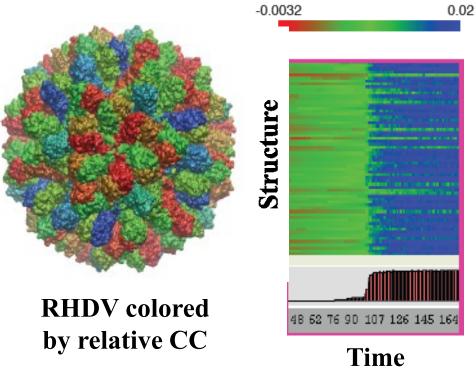
Parallel MDFF Cross Correlation Analysis on Cray XK7

Relative CC

Rabbit Hemorrhagic Disease Virus (RHDV)

Traj. frames	10,000
Structure component selections	720
Single-node XK7 (projected)	336 hours (14 days)
128-node XK7	3.2 hours 105x speedup
2048-node XK7	19.5 minutes 1035x speedup

Calculation of 7M CCs would take **5 years** using serial CPU algorithm!



Stone et al., Faraday Discuss., 169:265-283, 2014.

VMD Tesla P100 Cross Correlation Performance Rabbit Hemorrhagic Disease Virus: 702K atoms, 6.5Å resolution

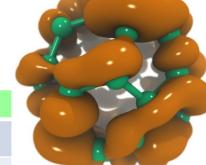
P100 Die-Stacked Mem Accelerates Bandwidth Intensive Calculation

Hardware platform	Runtime, Spee	dup vs. Chimera,	VMD+GPU
Chimera Xeon E5-2687W (2 socket) [1]	15.860s,	1x	
VMD-CPU IBM Power8 VSX SIMD (2 socket) [2]	1.334s,	12x	
VMD-CPU Intel Xeon E5-2660v3 SIMD (2 socket) [2]	0.905s,	17x	
VMD-CUDA IBM Power8 + 1x Tesla K40 [2]	0.488s,	32x	0.9x
VMD-CUDA Intel Xeon E5-2687W + 1x Quadro K6000 [1,2]	0.458s,	35x	1.0x
VMD-CUDA Intel Xeon E5-2698v3 + 1x Tesla P100	0.090s,	176x	5.1x
VMD-CUDA IBM Power8 "Minsky" + 1x Tesla P100	0.080s,	198x	5.7x

 GPU-Accelerated Analysis and Visualization of Large Structures Solved by Molecular Dynamics Flexible Fitting. J. E. Stone, R. McGreevy, B. Isralewitz, and K. Schulten. Faraday Discussions 169:265-283, 2014.
 Early Experiences Porting the NAMD and VMD Molecular Simulation and Analysis Software to GPU-Accelerated OpenPOWER Platforms. J. E. Stone, A.-P. Hynninen, J. C. Phillips, K. Schulten. International Workshop on OpenPOWER for HPC (IWOPH'16), LNCS 9945, pp. 188-206, 2016.



VMD Tesla P100 Performance for C₆₀ Molecular Orbitals, 516x519x507 grid

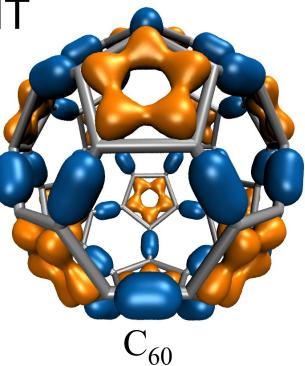


Hardware platform	Runtime,	Speedup		
IBM Power8 (2 socket) (ORNL 'crest') [1]	8.03s,	0.4x	- 5.	
Intel Xeon E5-2660v3 (2 socket) [1]	7.14s,	0.5x		
IBM Power8 (ORNL 'crest') + 1x Tesla K40 [1]	3.49s,	1.0x		
Intel Xeon E5-2698v3 + 1x Tesla P100	1.35s,	2.5x		
IBM Power8 "Minsky" + 1x Tesla P100	1.09s,	3.3x		
IBM Power8 (ORNL 'crest') + 4x Tesla K40 [1]	0.91s,	3.8x	NVLink perf. boost w/ no	
Intel Xeon E5-2698v3 + 4x Tesla P100	0.37s,	9.4x	code tuning	
IBM Power8 "Minsky" + 4x Tesla P100	0.30s,	11.6x	(YET)	

[1] Early Experiences Porting the NAMD and VMD Molecular Simulation and Analysis Software to GPU-Accelerated OpenPOWER Platforms. J. E. Stone, A.-P. Hynninen, J. C. Phillips, K. Schulten. International Workshop on OpenPOWER for HPC (IWOPH'16), LNCS 9945, pp. 188-206, 2016.

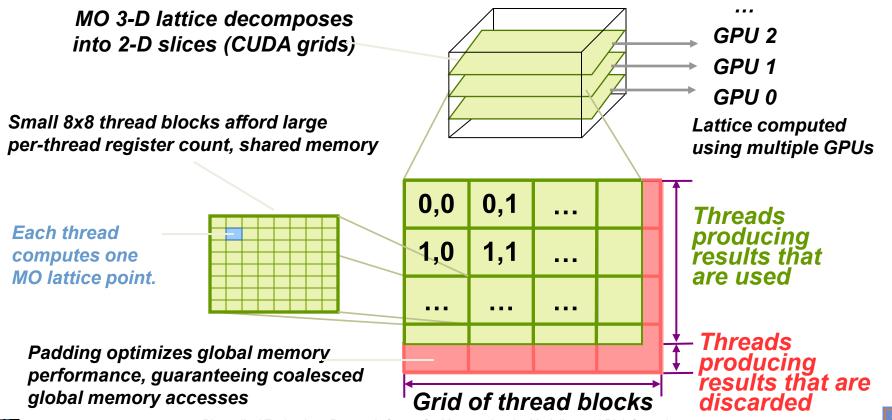
Molecular Orbitals w/ NVRTC JIT

- Visualization of MOs aids in understanding the chemistry of molecular system
- MO spatial distribution is correlated with probability density for an electron(s)
- **Animation** of (classical mechanics) molecular dynamics trajectories provides insight into simulation results
 - To do the same for QM or QM/MM simulations MOs must be computed at **10 FPS** or more
 - Large GPU speedups (up to 30x vs. current generation 4-core CPUs) over existing tools makes this possible!
- Run-time code generation (JIT) and compilation via CUDA NVRTC enable further optimizations and the highest performance to date: 1.8x faster than fully-general data-driven loops



High Performance Computation and Interactive Display of Molecular Orbitals on GPUs and Multicore CPUs. J. E. Stone, J. Saam, D. Hardy, K. Vandivort, W. Hwu, K. Schulten, 2nd Workshop on General-Purpose Computation on Graphics Processing Units (GPGPU-2), ACM International Conference Proceeding Series, volume 383, pp. 9-18, 2009.

MO GPU Parallel Decomposition



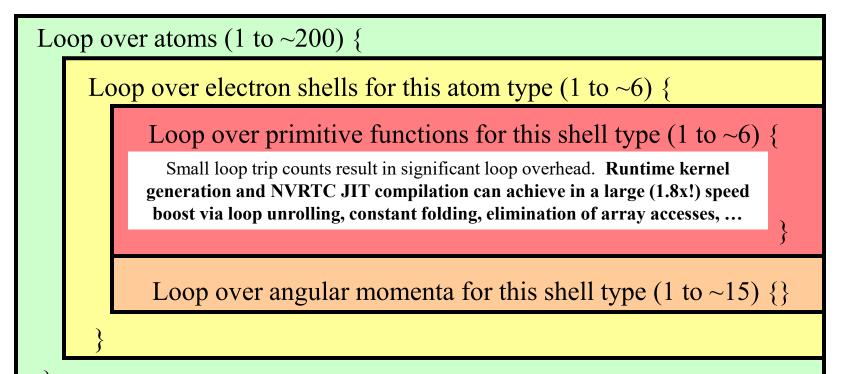


MO Kernel for One Grid Point (Naive C)

for (at=0; at <numatoms; at++)="" {<br="">int prim_counter = atom_basis[at]; <u>calc_distances_to_atom(&atompos[at], &xdist, &ydist, &zdist, &dist2, &xdiv);</u></numatoms;>	Loop over atoms
<pre>for (contracted_gto=0.0f, shell=0; shell < num_shells_per_atom[at]; shell++) { int shell type = shell symmetry[shell counter];</pre>	Loop over shells
<pre>for (prim=0; prim < num_prim_per_shell[shell_counter]; prim++) { float exponent = basis_array[prim_counter]; float contract_coeff = basis_array[prim_counter + 1]; contracted_gto += contract_coeff * expf(-exponent*dist2); prim_counter += 2; }</pre>	Loop over primitives: largest component of runtime, due to expf()
<pre>for (tmpshell=0.0f, j=0, zdp=1.0f; j<=shell_type; j++, zdp*=zdist) { int imax = shell_type - j; for (i=0, ydp=1.0f, xdp=pow(xdist, imax); i<=imax; i++, ydp*=ydist, xdp*=xdiv tmpshell += wave_f[ifunc++] * xdp * ydp * zdp; }</pre>	Loop over angular momenta (unrolled in real code)
<pre>value += tmpshell * contracted_gto; shell_counter++; }</pre>	

.

MO Kernel Structure, Opportunity for NRTC JIT... Data-driven execution, but representative loop trip counts in (...)



Molecular Orbital Computation and Display Process Runtime Kernel Generation, NVRTC Just-In-Time (JIT) Compilation

One-time initialization

Initialize Pool of GPU Worker Threads Read QM simulation log file, trajectory

Preprocess MO coefficient data

eliminate duplicates, sort by type, etc...

Generate/compile basis set-specific CUDA kernel

For current frame and MO index, retrieve MO wavefunction coefficients

For each trj frame, for each MO shown Compute 3-D grid of MO wavefunction amplitudes using basis set-specific CUDA kernel

Extract isosurface mesh from 3-D MO grid

Render the resulting surface

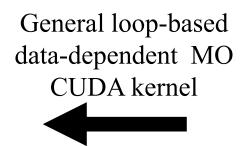
```
for (shell=0; shell < maxshell; shell++) {</pre>
```

float contracted_gto = 0.0f;

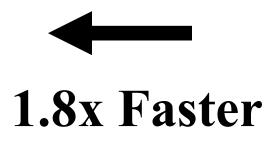
}

// Loop over the Gaussian primitives of CGTO
int maxprim = const_num_prim_per_shell[shell_counter];
int shell_type = const_shell_symmetry[shell_counter];
for (prim=0; prim < maxprim; prim++) {
 float exponent = const_basis_array[prim_counter];
 float contract_coeff = const_basis_array[prim_counter + 1];
 contracted_gto += contract_coeff * expf(-exponent*dist2);
 prim_counter += 2;</pre>

contracted_gto = 1.832937 * expf(-7.868272*dist2); contracted_gto += 1.405380 * expf(-1.881289*dist2); contracted_gto += 0.701383 * expf(-0.544249*dist2);



Runtime-generated dataspecific MO CUDA kernel compiled via CUDA NVRTC JIT...



```
for (shell=0; shell < maxshell; shell++) {
  float contracted gto = 0.0f;</pre>
```

// Loop over the Gaussian primitives of CGTO
int maxprim = const_num_prim_per_shell[shell_counter];
int shell_type = const_shell_symmetry[shell_counter];
for (prim=0; prim < maxprim; prim++) {</pre>

```
float exponent = const_basis_array[prim_counter ];
float contract_coeff = const_basis_array[prim_counter + 1];
contracted_gto += contract_coeff * expf(-exponent*dist2);
prim_counter += 2;
```

```
}
```

```
float tmpshell=0;
```

```
switch (shell_type) {
```

```
case S_SHELL:
```

```
value += const_wave_f[ifunc++] * contracted_gto;
break;
```

```
[....]
```

```
case D_SHELL:
```

```
tmpshell += const_wave_f[ifunc++] * xdist2;
tmpshell += const_wave_f[ifunc++] * ydist2;
tmpshell += const_wave_f[ifunc++] * zdist2;
tmpshell += const_wave_f[ifunc++] * xdist * ydist;
```

General loop-based data-dependent MO CUDA kernel

Runtime-generated dataspecific MO CUDA kernel compiled via **CUDA NVRTC** JIT...



```
1.8x Faster
```

contracted_gto = 1.832937 * expf(-7.868272*dist2); contracted_gto += 1.405380 * expf(-1.881289*dist2); contracted_gto += 0.701383 * expf(-0.544249*dist2); // P_SHELL tmpshell = const_wave_f[ifunc++] * xdist; tmpshell += const_wave_f[ifunc++] * ydist;

tmpshell += const_wave_f[ifunc++] * zdist; value += tmpshell * contracted gto;

contracted_gto = 0.187618 * expf(-0.168714*dist2);
// S_SHELL
value += const wave f[ifunc++] * contracted gto;

contracted_gto = 0.217969 * expf(-0.168714*dist2); // P_SHELL tmpshell = const_wave_f[ifunc++] * xdist; tmpshell += const_wave_f[ifunc++] * ydist; tmpshell += const_wave_f[ifunc++] * zdist; value += tmpshell * contracted_gto;

contracted_gto = 3.858403 * expf(-0.800000*dist2); // D_SHELL tmpshell = const_wave_f[ifunc++] * xdist2; tmpshell += const_wave_f[ifunc++] * ydist2;

Challenges Adapting Large Software Systems for State-of-the-Art Hardware Platforms

- Initial focus on key computational kernels eventually gives way to the need to optimize an ocean of less critical routines, due to observance of Amdahl's Law
- Even though these less critical routines might be easily ported to CUDA or similar, the sheer number of routines often poses a challenge
- Need a low-cost approach for getting "some" speedup out of these second-tier routines
- In many cases, it is completely sufficient to achieve memorybandwidth-bound GPU performance with an existing algorithm



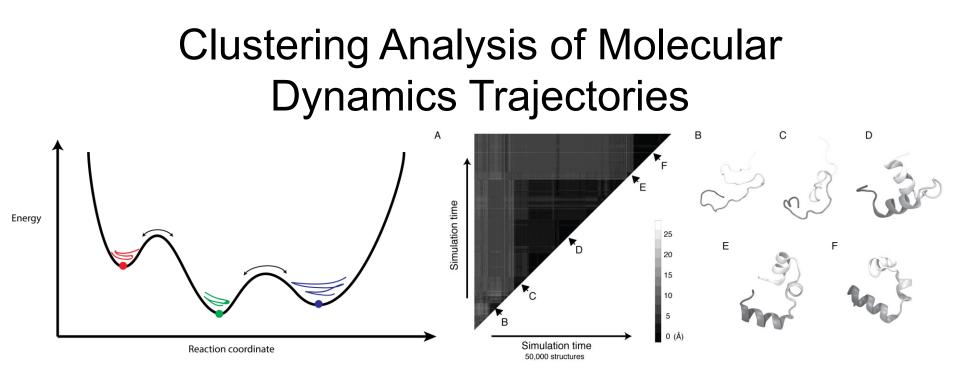


Directive-Based Parallel Programming with OpenACC

- Annotate loop nests in existing code with #pragma compiler directives:
 - Annotate opportunities for parallelism
 - Annotate points where host-GPU memory transfers are best performed, indicate propagation of data
- Evolve original code structure to improve efficacy of parallelization
 - Eliminate false dependencies between loop iterations
 - Revise algorithms or constructs that create excess data movement







GPU-Accelerated Molecular Dynamics Clustering Analysis with OpenACC. J.E. Stone, J.R. Perilla, C. K. Cassidy, and K. Schulten. In, Robert Farber, ed., Parallel Programming with OpenACC, Morgan Kaufmann, Chapter 11, pp. 215-240, 2016.



Serial QCP RMSD Inner Product Loop

- Simple example where directive based parallelism can be applied easily and effectively
- Such a loop is inherently a memory-bandwidth-bound algorithm, so that's the goal for acceleration

for (int I=0; I<cnt; I++) { double x1, x2, y1, y2, z1, z2; x1 = crdx1[l];y1 = crdy1[l];z1 = crdz1[1]: G1 += x1*x1 + y1*y1 + z1*z1;x2 = crdx2[l]; $y^{2} = crdy^{2}[1];$ $z_2 = crdz_2[1];$ $G2 += x2^{*}x2 + y2^{*}y2 + z2^{*}z2;$ a0 += x1 * x2: a1 += x1 * y2; a2 += x1 * z2; a3 += v1 * x2: a4 += y1 * y2; a5 += y1 * z2; a6 += z1 * x2; a7 += z1 * v2: a8 += z1 * z2:



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OpenACC QCP RMSD Inner Product Loop

- Simple example where directive based parallelism can be applied easily and effectively
- Such a loop is inherently a memory-bandwidth-bound algorithm, so that's the goal for acceleration

long i, j, k;

#pragma acc kernels copyin(crds[0:tsz]), copy(rmsdmat[0:msz])
for (k=0; k<(framecount*(framecount-1))/2; k++) {
 // compute triangular matrix index 'k' in a helper function
 // to ensure that the compiler doesn't think that we have
 // conflicts or dependencies between loop iterations
 acc_idx2sub_tril(long(framecount-1), k, &i, &j);
 long x1addr = j * 3L * framecrdsz;
 long x2addr = i * 3L * framecrdsz;</pre>

#pragma acc loop vector(256) for (long l=0; l<cnt; l++) { // abridged for brevity ...</pre>

```
rmsdmat[k]=rmsd; // store linearized triangular matrix }
```



OpenACC QCP RMSD Inner Product Loop Performance Results

- Xeon 2687W v3, w/ hand-coded AVX and FMA intrinsics: 20.7s
- Tesla K80 w/ OpenACC: 6.5s (3.2x speedup)
- OpenACC on K80 achieved 65% of theoretical peak memory bandwidth, with 2016 compiler and just a few lines of #pragma directives. Excellent speedup for minimal changes to code.
- Future OpenACC compiler revs should provide higher performance yet

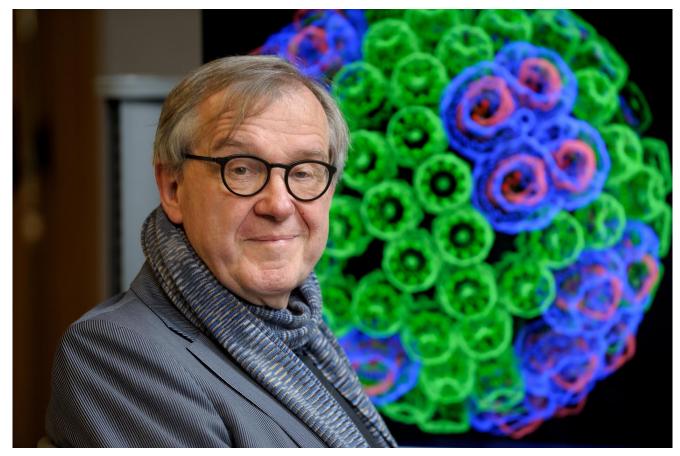


Acknowledgements

- Theoretical and Computational Biophysics Group, University of Illinois at Urbana-Champaign
- CUDA Center of Excellence, University of Illinois at Urbana-Champaign
- NVIDIA CUDA and OptiX teams
- Funding:
 - DOE INCITE, ORNL Titan: DE-AC05-00OR22725
 - NSF Blue Waters: NSF OCI 07-25070, PRAC "The Computational Microscope", ACI-1238993, ACI-1440026
 - NIH support: 9P41GM104601, 5R01GM098243-02







"When I was a young man, my goal was to look with mathematical and computational means at the inside of cells, one atom at a time, to decipher how living systems work. That is what I strived for and I never deflected from this goal." – Klaus Schulten

Related Publications http://www.ks.uiuc.edu/Research/gpu/

- Challenges of Integrating Stochastic Dynamics and Cryo-electron Tomograms in Whole-cell Simulations.
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- Immersive Molecular Visualization with Omnidirectional Stereoscopic Ray Tracing and Remote Rendering. J. E. Stone, W. R. Sherman, and K. Schulten. High Performance Data Analysis and Visualization Workshop, IEEE International Parallel and Distributed Processing Symposium Workshop (IPDPSW), pp. 1048-1057, 2016.
- **High Performance Molecular Visualization: In-Situ and Parallel Rendering with EGL.** J. E. Stone, P. Messmer, R. Sisneros, and K. Schulten. High Performance Data Analysis and Visualization Workshop, IEEE International Parallel and Distributed Processing Symposium Workshop (IPDPSW), pp. 1014-1023, 2016.
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- Quantifying the Impact of GPUs on Performance and Energy Efficiency in HPC Clusters. J. Enos, C. Steffen, J. Fullop, M. Showerman, G. Shi, K. Esler, V. Kindratenko, J. Stone, J Phillips. *International Conference on Green Computing*, pp. 317-324, 2010.
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