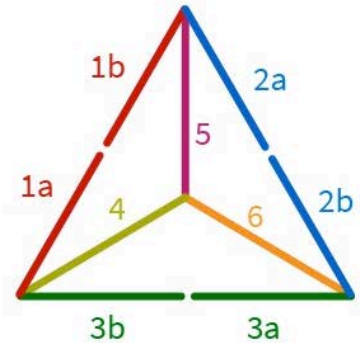
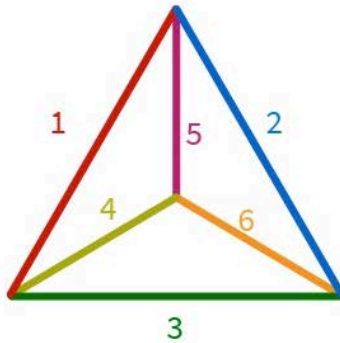
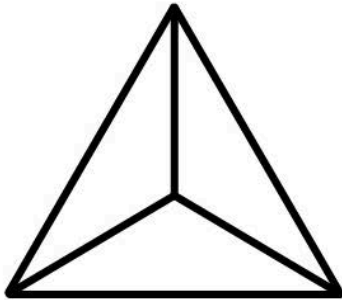


Design 3: Wireframe Tetrahedron

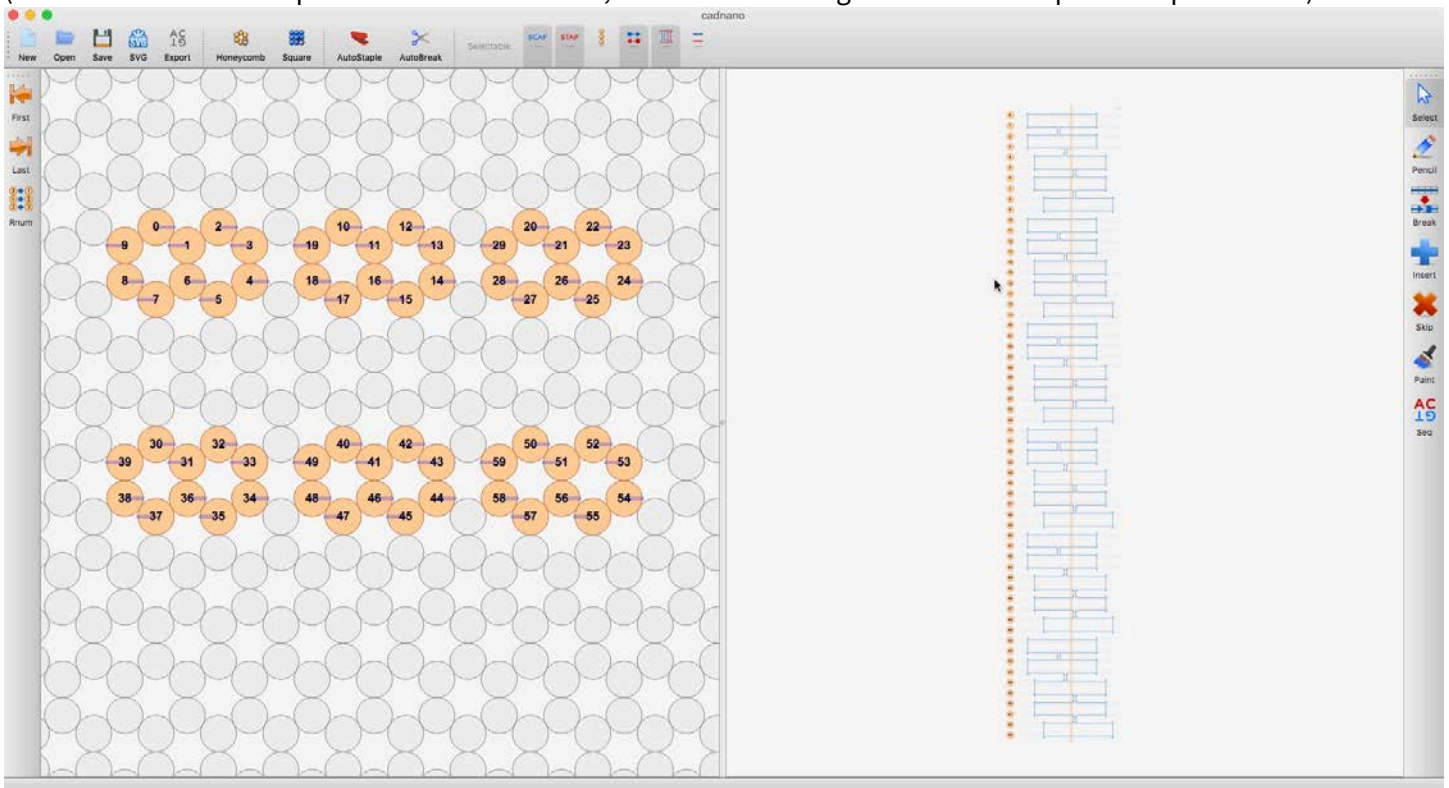
Step 1: Starting with a Schlegel diagram, decide which edges are going to be split to avoid any closed loops in the graph.

This diagram is drawn manually in Illustrator.



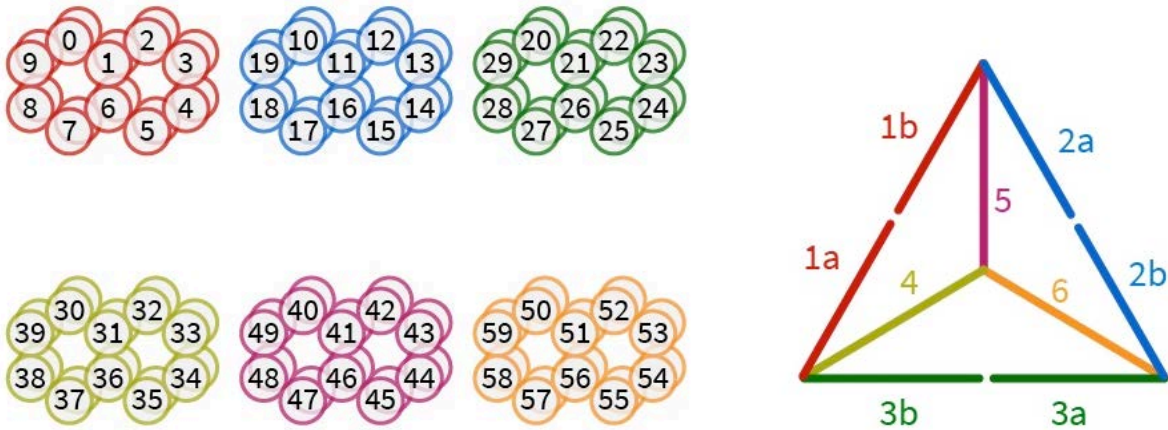
Step 2: Create strut cross-sections in Cadnano

We use six 10-helix bundles. Once the basic cross-section is defined, use **Cadnano1** to export the SVG diagram. (Cadnano2 SVG doesn't provide the cross-section, but we are working on a new SVG exporter as part of CTK).



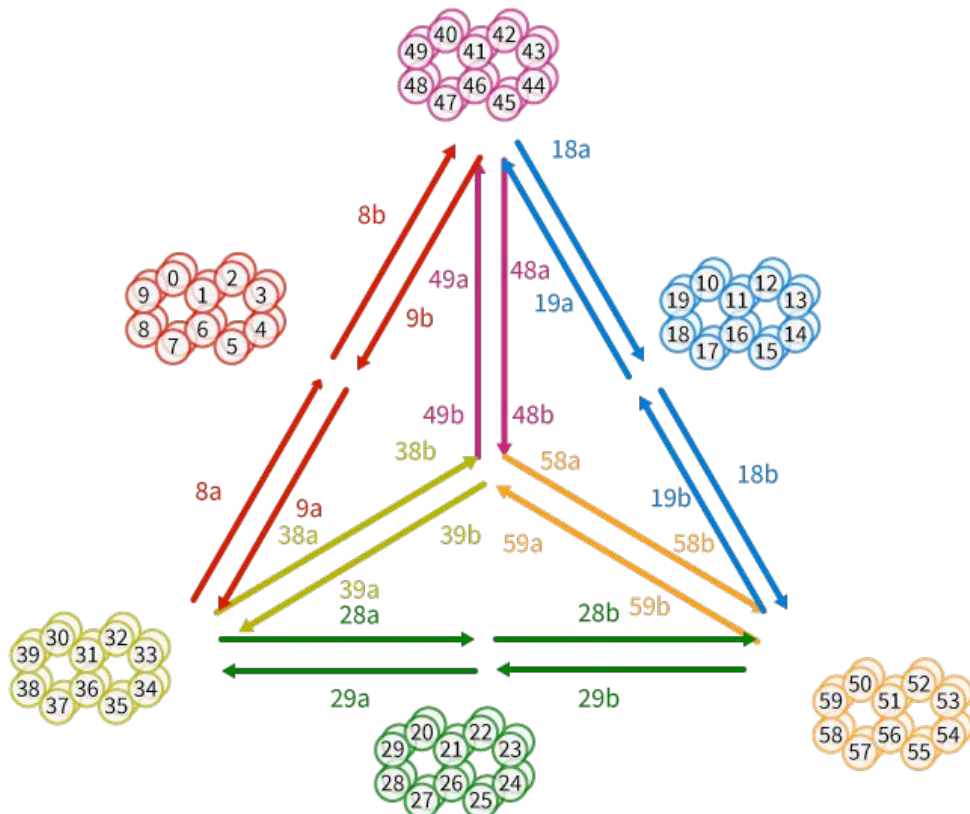
Step 3: Import the SVG and stylize the Virtual Helices.

Assign colors to the different struts to match the Schlegel diagram. You can duplicate the circles and apply a white fill with some transparency to the front circles to get a “pseudo 3D” effect.



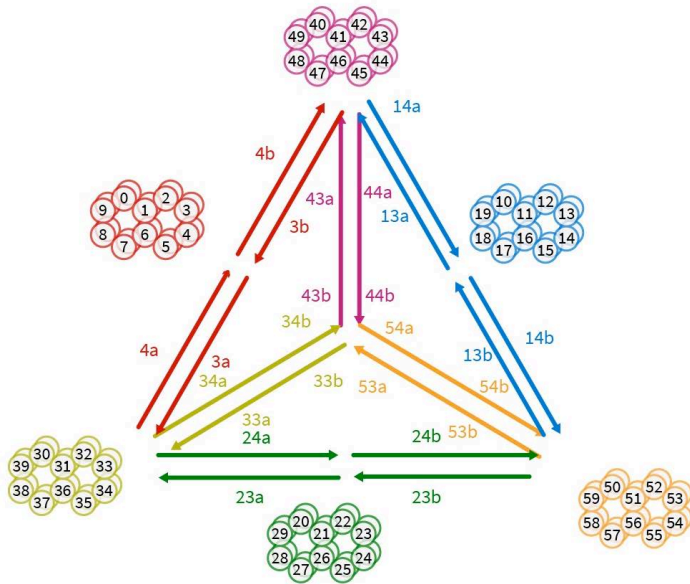
Step 4: Re-draw the Schlegel diagram

Double the lines to include “fwd” and “rev” paths to correspond to “even” and “odd” helices in our design. Number the edge segments to match the helix numbers for the corresponding strut. Add arrows to indicate 3' ends.



Step 5: Trace a complete path through the segments and note connection pairs

Working clockwise starting at segment **4b**, it connects to **14a**, which crosses over to **13a**, which connects to **44a**, and so on. We keep track of these pairings in a text editor.



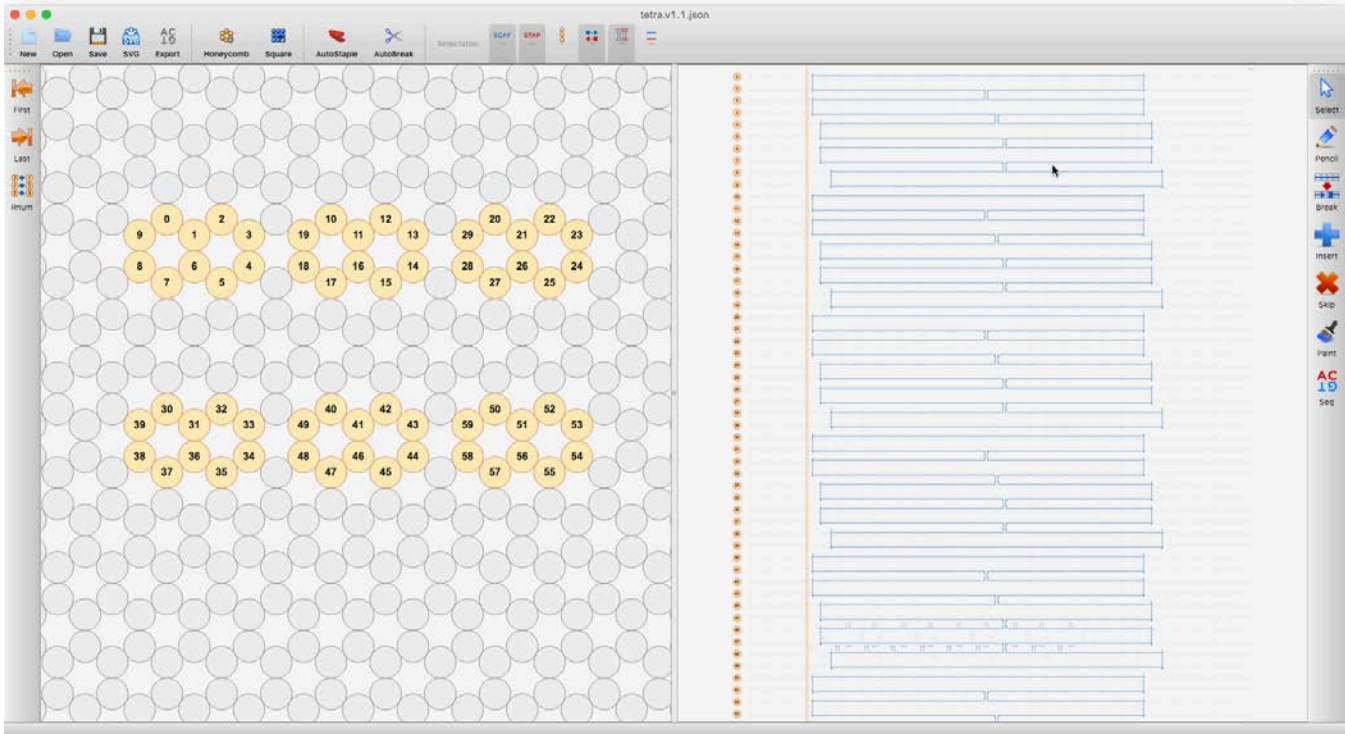
```

1 4b: 14a
2 13a: 44a
3 44b: 54a
4 54
5 14b: 23b
6 24b: 53b
7 53a: 33b
8 33a: 24a
9 23a: 4a
10 3a: 34a
11 34b: 43b
12 43a: 3b
13

```

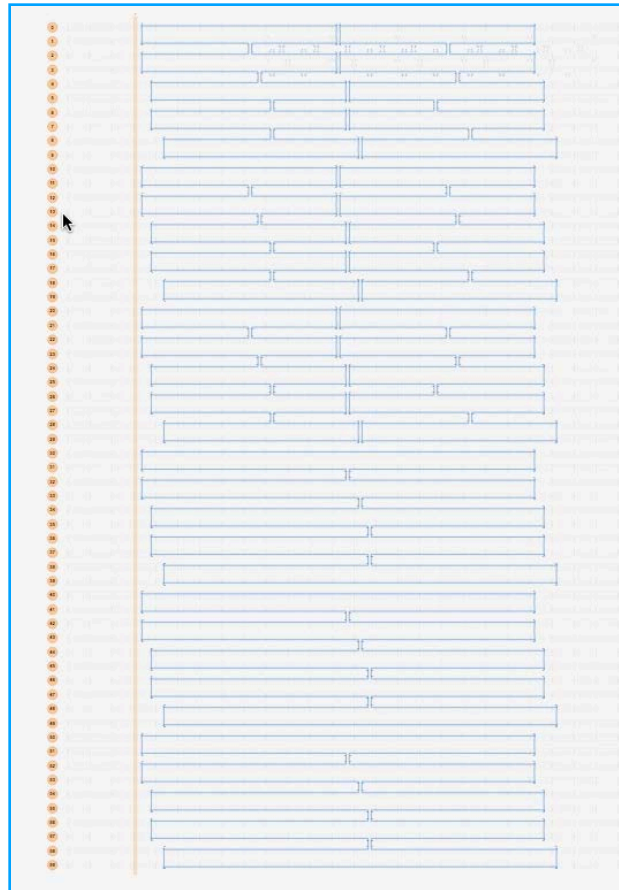
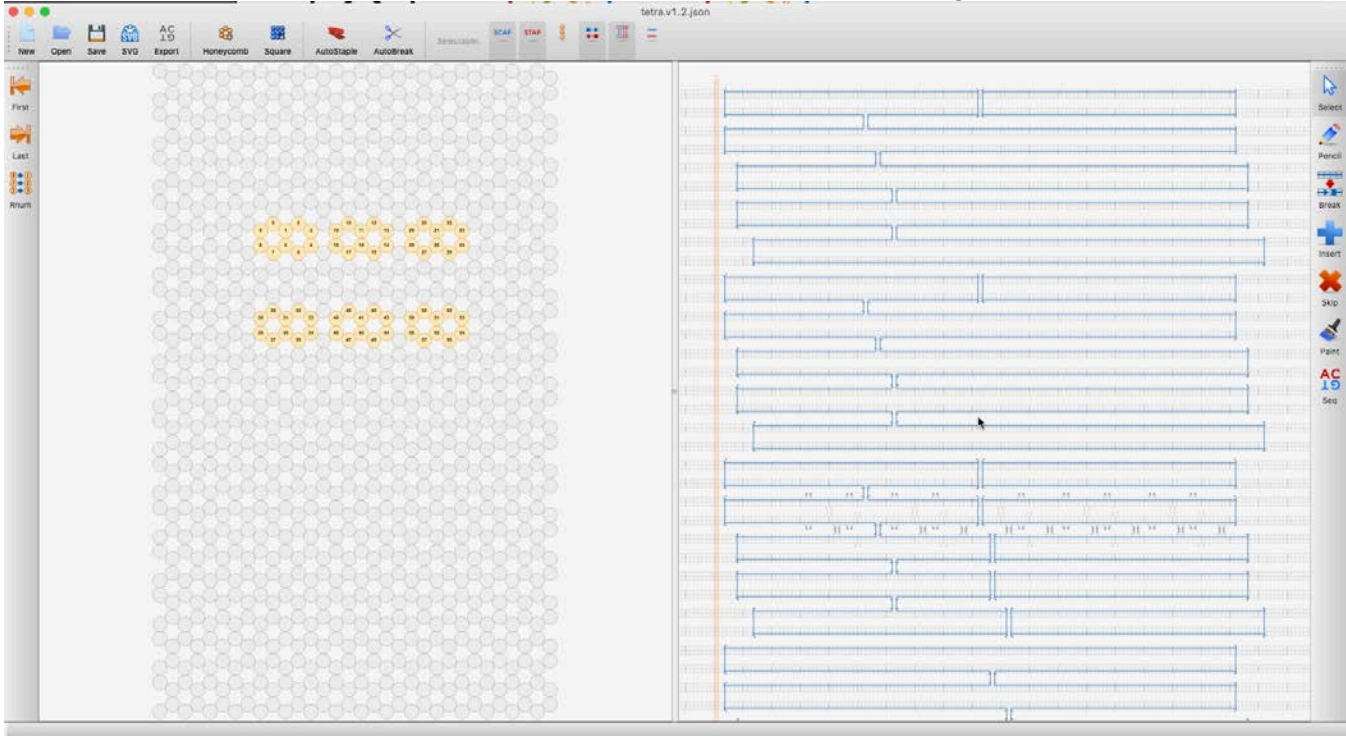
Step 6: Return to the Cadnano design and extrude the struts to desired lengths

Make sure the sum of the lengths matches the desired scaffold length, e.g. $6 \times 1344 = 8064$



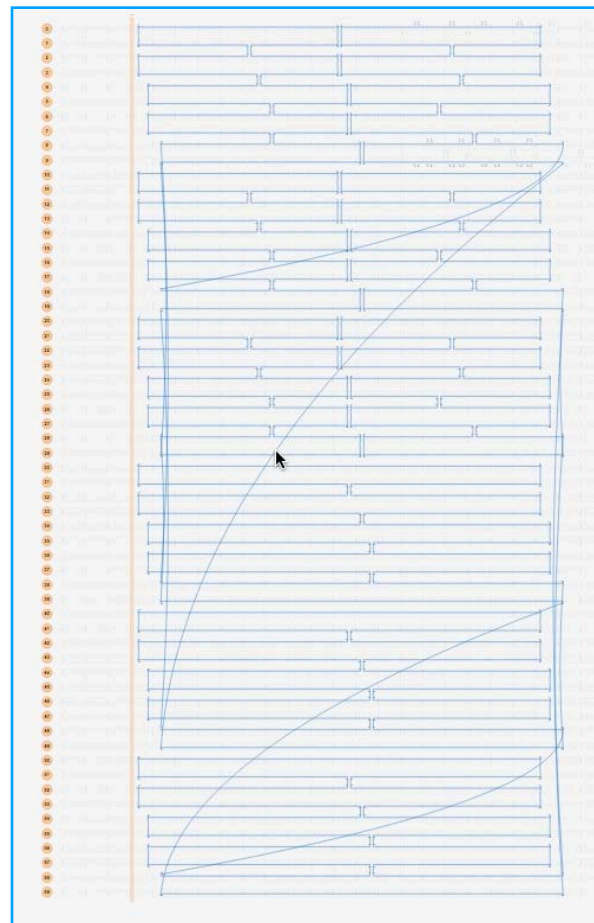
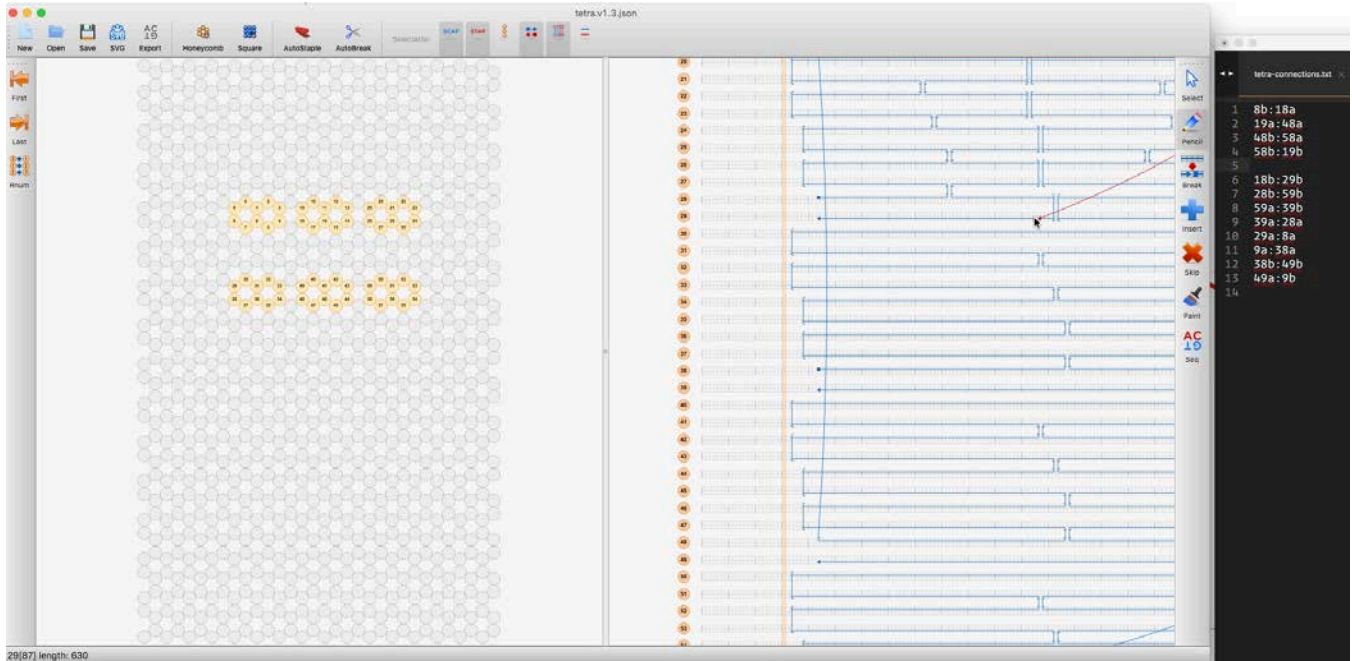
Step 7: Install Scaffold crossovers to split the appropriate struts in half.

We must also install new seams in the half-struts to avoid any disconnected segments.



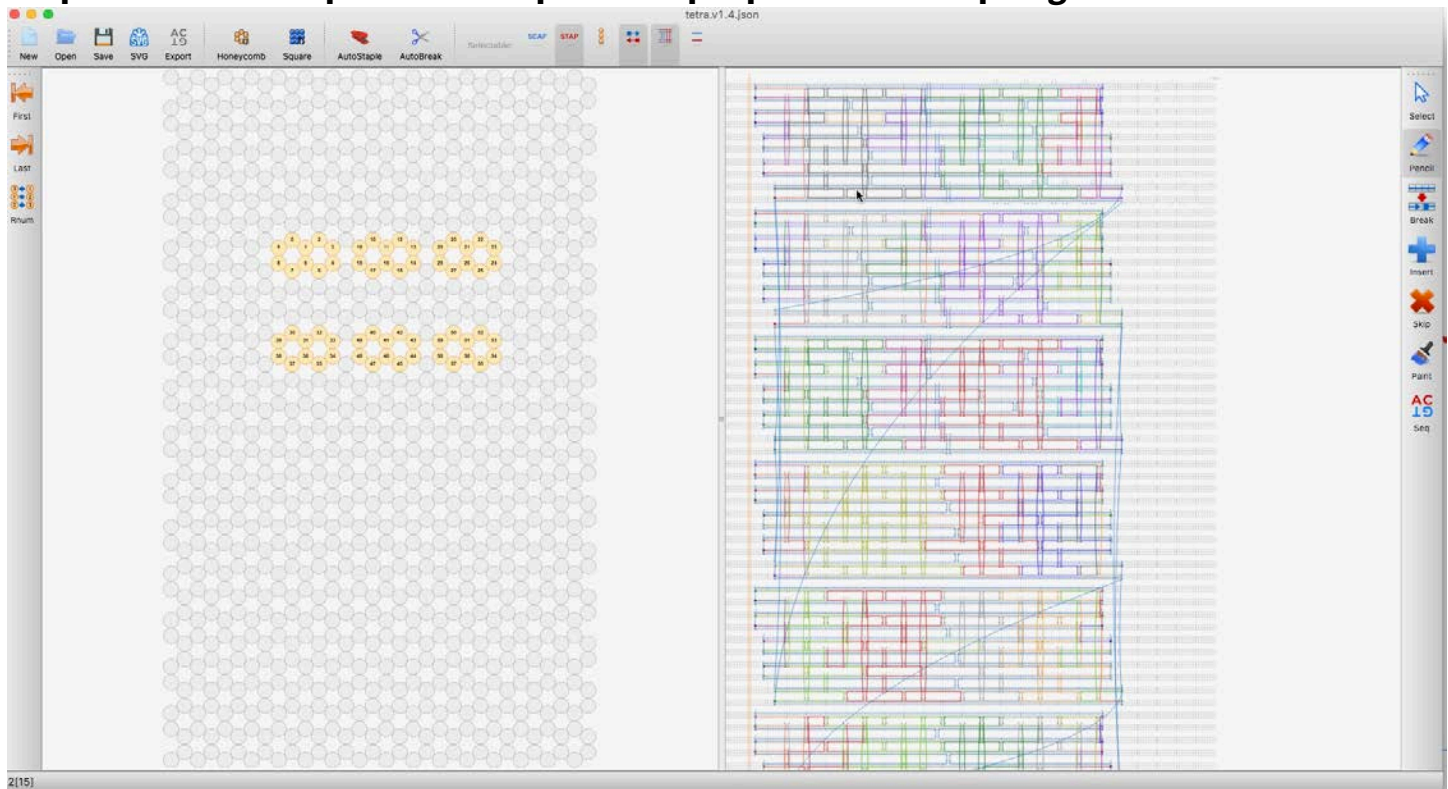
The updated scaffold layout.

Step 8: Use the Pencil tool to force-install the vertex connections in the scaffold.



The final scaffold layout.

Step 9: Use AutoStaple to create proto-staple paths. Clean up edges as usual.



Step 10: Transfer design to the AMI and run AutoBreak

The screenshot shows a VNC Viewer window titled 'ctk-1 (ip-172-31-10-92:0) - VNC Viewer'. The desktop environment is Ubuntu. A terminal window is open, showing the following commands and output:

```

general) ubuntu@ip-172-31-10-92:~$ cd
general) ubuntu@ip-172-31-10-92:~$ cd Dropbox\_(DouglasLab)\
general) ubuntu@ip-172-31-10-92:~/Dropbox (DouglasLab)$ ls
brick_v1.1_autobreak_001  brick_v1.1.json  tetra.v1.5.json
general) ubuntu@ip-172-31-10-92:~/Dropbox (DouglasLab)/AMI-swap$ history | grep auto
141 sudo apt-get install autocutsel
197 autobreak.py
198 autobreak.py -i brick_v1.1.json
200 autobreak.py -i brick_v1.1.json -rule xstap.all3 -seq p7560
202 autobreak.py -i brick_v1.1.json -rule xstap.all3 -seq p7560
204 origamisim.py -i brick_v1.1_autobreak_001/brick_v1.1_autobreak_legacy.js
205 origamisim.py -i brick_v1.1_autobreak_001/brick_v1.1_autobreak_legacy.js
-vmd
212 history | grep auto
general) ubuntu@ip-172-31-10-92:~/Dropbox (DouglasLab)/AMI-swap$ autobreak.py -
tetra.v1.5.json -rule xtap.all3 -seq p7560
reading file tetra.v1.5.json
found cadnano version 2 file

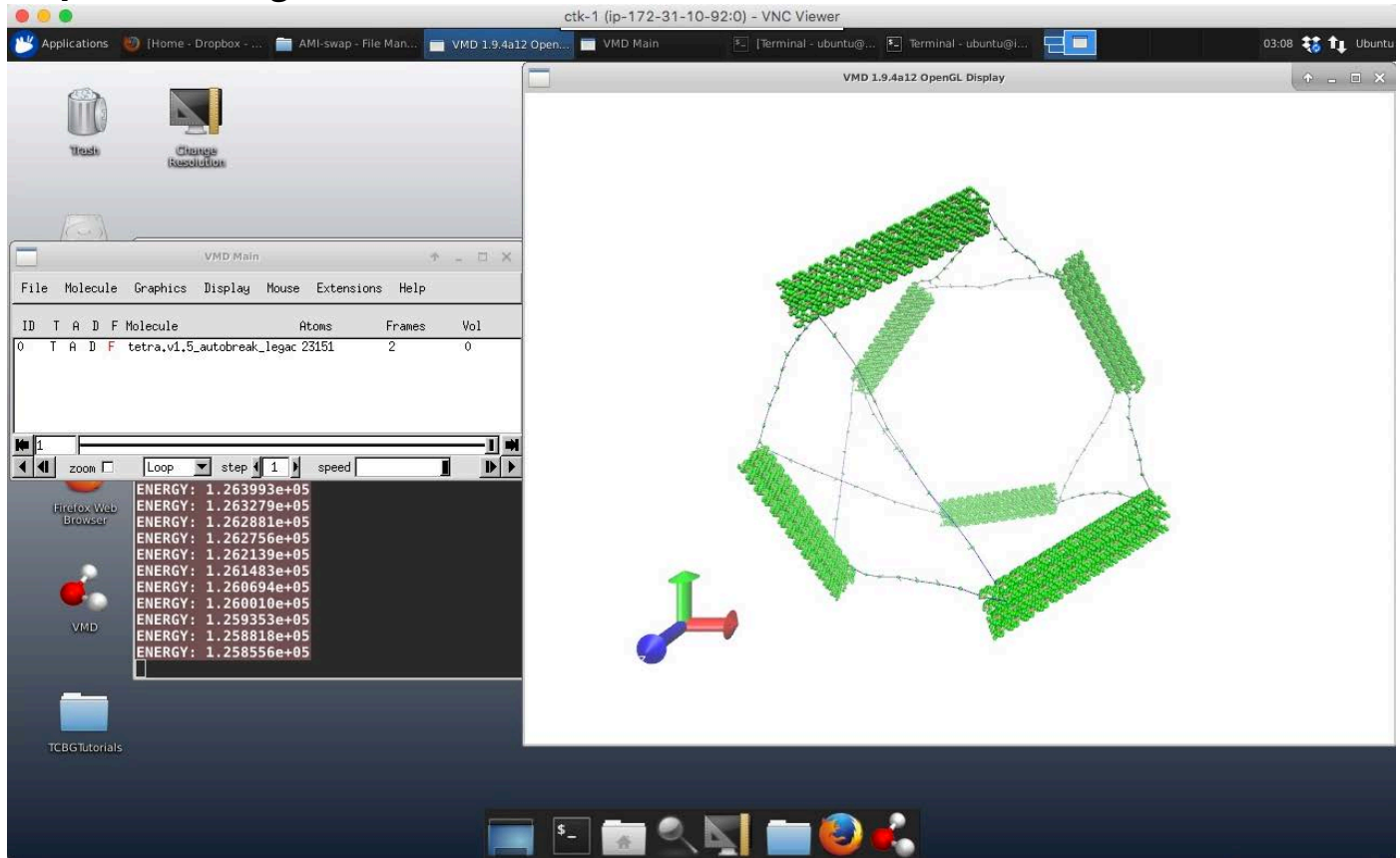
```

A file manager window titled 'AMI-swap - File Manager' is also open, showing the contents of the directory '/home/ubuntu/Dropbox (DouglasLab)/AMI-swap/':

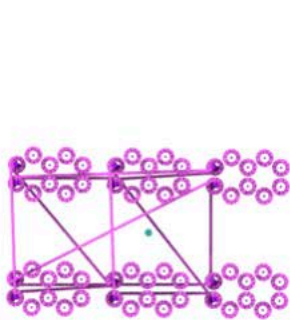
| Name | Size | Type | Date Modified |
|--------------------------|----------|---------------|---------------|
| brick_v1.1_autobreak_001 | 4.1 kB | folder | Thursday |
| tetra.v1.5_autobreak_001 | 4.1 kB | folder | Today |
| brick_v1.1.json | 337.2 kB | JSON document | Thursday |
| tetra.v1.5.json | 377.7 kB | JSON document | Today |

The terminal window also shows the output of the 'history' command, which includes the command 'autobreak.py -i brick_v1.1.json -rule xstap.all3 -seq p7560'.

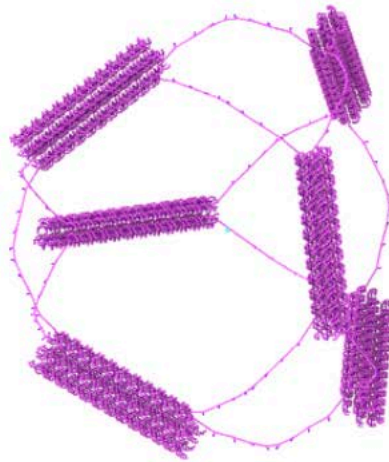
Step 11: Run OrigamiSim



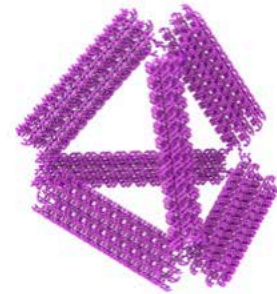
Assuming you are working in your Dropbox swap folder, you should be able to open the **.gsd** files in **Ovito**.



Frame 0



Frame 9



Frame 32

Example Ovito renders of frames 0, 9, and 32 of the tetra.v1 simulation