Visualizing Biomolecular Complexes with VMD

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Overview

- Brief intro to VMD
- Challenges presented by the driving science projects
- Graphics technology driving molecular visualization capabilities and performance
- Future directions for molecular visualization



VMD

- VMD "Visual Molecular Dynamics"
- Visualization of molecular dynamics simulations, sequence data, volumetric data, quantum chemistry data, particle systems
- User extensible with scripting and plugins
- http://www.ks.uiuc.edu/Research/vmd/





VMD Advanced Data Handling



VMD Takes Advantage of Emerging Technological Opportunities

- 8- and 12-core CPUs common by 2010...
- Graphics processors (GPUs) have over 240 processing units, and frequently achieve speedups of 8-30x vs. CPUs
- Parallel processing is now **required** to increase performance
- Several VMD algorithms are now parallelized for multi-core CPUs and GPUs
- Continued developments will more broadly benefit rendering and analysis features of VMD



Goal: A Computational Microscope

• Study the molecular machines in living cells

Ribosome: synthesizes proteins from genetic information, target for antibiotics



Silicon nanopore: bionanodevice for sequencing DNA efficiently





What the Computational Microscope Sees

- Sees the calculated motions of the molecular machines
- Ankyrin repeat protein being stretched out...
- Results compared between computer simulation and atomic force microscope experiments





Structure Building, Simulation Preparation

- Obtain atomic structure, e.g. from the Protein Data Bank
- Integrate structure into its native biological environment:
 - Membrane
 - Water
 - Ions
- Display and analyze the prepared system





Molecular Dynamics

- Classical mechanical simulation of atomic motions (F=ma)
- Molecular dynamics calculations save trajectories of atomic coordinates as the simulation progresses
- Researchers study trajectories by analyzing force profiles, energies, structural changes etc





Simulation of Biological Molecules

- All-atom models of proteins, membranes, DNA, in water solution
- Classical mechanics N-body algorithms are O(N log N) at best
- N = 100K to 10M atoms today, soon up to 100M atoms
- 512 CPU jobs often run on remote supercomputers for weeks at a time for a 10ns simulation
- Visualization and analysis require workstations with 4-32 GB of RAM, 1-4 CPUs, high-end graphics accelerators





The Computational Microscope in Virology

- Simulations lead to better understanding of the mechanics of viral infections
- Better understanding of infection mechanics at the molecular level may result in more effective treatments for diseases
- Since viruses are large, their computational viewing requires tremendous resources, in particular large parallel computers





Building, Viewing, Analyzing the Virus: VMD Software





Preparing the Virus for Simulation

- Key task: placement of ions inside and around the virus
- Virus ion placement ran for 110 CPU-hours on SGI Altix Itanium2
- Same calculation took 27 GPUminutes on GeForce 8800GTX with CUDA implementation
- Over 240 times faster: ion placement can now be done on a desktop machine!
- New linear-time GPU algorithm (multilevel summation) will speed this up even further





Complete Virus Model

Satellite Tobacco Mosaic Virus 932,508 atoms





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Simulating the Virus: NAMD Software





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Timeline: Graphics Hardware Used for Molecular Visualization

60's and 70's:

Mainframe-based vector graphics on Tektronix terminals,

Evans & Sutherland image generators

80's:

Transition to raster graphics on Unix workstations, Mac, PC

Space-filling molecular representations

Stereoscopic rendering

90's - 2002:

3rd-generation raster graphics systems

Depth-cueing

Texture mapping: coloring by potential, density, etc

Full-scene antialiasing

2002-present:

Programmable shading, GPU-acceleration of geometry calculations, ...



Comparison of Molecular Visualization with Other Graphics Intensive Applications

- Geometric complexity often limits molecular visualization performance
- All atoms move every simulation timestep, thwarts many LOD simplification techniques
- Commodity graphics hardware is tuned for requirements of games
- Solution: Use sophisticated shading instead of explicit geometry where possible









VMD Visualization Engine

•Simplified diagram only illustrates key stages

•VMD caches reusable data at each stage





Multi-modal Visualization

- Aligned sequences and structures, phylogeny
- Simultaneous use of shape, color, topology, and interactivity
- Multiple simultaneous representations
- Multiple data display modalities
- Selections in one modality can be used to highlight or select in others





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Displaying 10M Atom Complexes

- Uncompressed atom coordinates 120MB (3 floats/atom)
- Avoid traversal of per-atom data, hierarchical data structures are a must
- Caching, lazy evaluation, multithreading, overlapped rendering with computation
- Geometry caching, symmetry/instancing accelerate static structure display
- Representation geometry often 10-50x size of atom coordinate data, but is largely ephemeral

Programmable Graphics Hardware

Groundbreaking research systems: AT&T Pixel Machine (1989): 82 x DSP32 processors UNC PixelFlow (1992-98): 64 x (PA-8000 + 8,192 bit-serial SIMD) SGI RealityEngine (1990s): Up to 12 i860-XP processors perform

vertex operations (*u*code), fixedfunc. fragment hardware

All mainstream GPUs now incorporate programmable processors

UNC PixelFlow Rack

Reality Engine Vertex Processors

Early Experiments with Programmable Graphics Hardware in VMD

- Sun XVR-1000/4000 (2002)
 - 4xMAJC-5200 CPUs
 - 1GB Texture RAM
 - 32MB ucode RAM
 - 1 Teraflop Antialiasing Filter Pipeline
- Custom *u*code and OpenGL extension for rendering spheres
 - Draw only half-spheres, with solid side facing the viewer
 - 1-sided lighting
 - Host CPU only sends arrays of radii, positions, colors
 - Fast DMA engines copy arrays from system memory to GPU
 - Overall performance was over twice as fast, host CPU load significantly decreased

Peak Single-precision Arithmetic Performance Trend, GPU vs. CPU

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Evolution of Molecular Graphics Software Design

- Given ongoing trends:
 - Increasing size and complexity of simulations
 - Increased demand for interactivity in all stages of modeling, visualization, and analysis
 - Relative floating point performance and memory bandwidth of GPUs vs CPUs
- Highly parallelizable work must shift to GPUs
- CPU cores retain high level functions and coarse parallelism not suited to GPUs

Offloading More of Molecular Graphics and Modeling Work to the GPU

- Graphics related work first to go, adjust algorithms to favor higher GPU utilization:
 - GPU must generate geometry itself, not enough CPU-GPU bandwidth otherwise, particularly for trajectory animation
 - Use programmable shading rather than finely tessellated surface geometry
 - Proxy objects, ray casting
- Begin moving highly parallel modeling algorithms to the GPU (e.g. CUDA)

Benefits of Programmable Shading

- Potential for superior image quality with better shading algorithms
- Direct rendering of:
 - Quadric surfaces
 - Density map data, solvent surfaces
- Offload work from host CPU to GPU

Rendering Non-polygonal Data with Present-day Programmable Shading

- Algorithms mapped to vertex/fragment shading model available in current hardware
- Render by drawing bounding box or a viewer-directed quad containing shape/data
- Vertex shader sets up
- Fragment shader performs all the work

Contained object could be anything one can render in a point-sampled manner (e.g. scanline rendering or ray tracing of voxels, triangles, spheres, cylinders, tori, general quadric surfaces, etc...)

Ray Traced Sphere Rendering with Programmable Shading

- Fixed-function OpenGL requires curved surfaces to be tessellated with triangles, lines, or points
- Fine tessellation required for good results with Gouraud shading; performance suffers
- Static tessellations look bad when viewer zooms in
- Dynamic tessellation too costly when animating huge trajectories
- Programmable shading solution:
 - Ray trace spheres in fragment shader
 - GPU does all the work
 - Spheres look good at all zoom levels
 - Rendering time is proportional to pixel area covered by sphere
 - Overdraw is a bigger penalty than for triangulated spheres

Programmable Shading: 12 triangle bounding box, or 1 viewer-directed quad

Sphere Fragment Shader

- Written in OpenGL Shading Language
- High-level C-like language with vector types and operations
- Compiled dynamically by the graphics driver at *runtime*
- Compiled machine code executes on GPU

VMD Sphere Fragment Shader (not for normal geometry)

>id main(void) {
 vec3 raydir = normalize(V);
 vec3 spheredir = spherepos - rayorigin;

// Perform ray-sphere intersection tests based on the code in Tachyon
float b = dot(raydir, spheredir);
float temp = dot(spheredir, spheredir);
float disc = b*b + sphereradsg - temp;

// only calculate the nearest intersection, for speed if (disc $\leq=0_{\star}0)$ discard; // ray missed sphere entirely, discard fragment

```
// calculate closest intersection
float tnear = b - sqrt(disc);
```

```
if (tnear < 0.0)
discard;
```

```
// calculate hit point and resulting surface normal
vec3 pnt = rayorigin + tnear * raydir;
vec3 N = normalize(pnt - spherepos);
```

```
// Output the ray-sphere intersection point as the fragment depth
// rather than the depth of the bounding box polygons.
// The eye coordinate Z value must be transformed to normalized device
// coordinates before being assigned as the final fragment depth.
if (vmdprojectionmode == 1) {
    // perspective projection = 0.5 + (hfpn + (f * n / pnt.z)) / diff
    gl_FragDepth = 0.5 + (vmdprojparms[2] + (vmdprojparms[1] * vmdprojparms[0]
3];
} else {
    // orthographic projection = 0.5 + (-hfpn - pnt.z) / diff
    gl_FragDepth = 0.5 + (-vmdprojparms[2] - pnt.z) / vmdprojparms[3];
}
```

```
#ifdef TEXTURE
    // perform texturing operations for volumetric data
    // The only texturing mode that applies to the sphere shaden
```


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Shading Comparison: EF-Tu

VMD Interactive OpenGL Rendering

VMD/Tachyon

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Efficient 3-D Texturing of Large Datasets

- MIP mapping, compressed map data
- Perform volumetric color transfer functions on GPU rather than on the host CPU
 - perform all range clamping and density-to-color mapping on GPU
 - update color transfer function without redownloading large texture maps

Strategies for Working Within GPU Hardware Constraints

- Most GPUs <= 1GB RAM currently
- Use bricked data, multi-level grids, viewdependent map resolution
- Use occlusion culling to prevent rendering of bricks that aren't visible, thus avoiding texture download/access
- Use reduced precision FP types for surface normal / gradient maps

Further GPU Acceleration

- Atomic representation tessellation, spline calculations, atom selections, spatial queries computed entirely on GPU
- Direct rendering of isosurfaces from volumetric data via ray casting (e.g. electron density surfaces, codes exist already)
- Computation and direct rendering of metaball ("Blob") approximation of molecular surfaces via ray casting (codes exist already)

Computing Volumetric Properties

- Compute density, distance, occupancy, potential maps for a frame or averaged over a trajectory
- Well suited to GPU acceleration
- Example: display binding sites for diffusively bound ions as probability density isosurfaces

tRNA magnesium ion occupancy

VMD Visualization Engine, GPU Acceleration Opportunities

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The Wheel of Reincarnation: Revival of Molecular Graphics Techniques?

- Graphics hardware is making another trip around the wheel of reincarnation (Myer and Sutherland CACM '68)
- Visualization techniques that weren't triangle-friendly lost favor in the 90's may return
- Algorithms that mapped poorly to fixed-function OpenGL are often easier to implement with programmable shading
- Non-polygonal geometry can now be rendered entirely on the GPU itself

Connolly surface consisting of sphere/torus patches

Next-Gen Graphics Architectures

- New programmable pipeline stages: geometry shader, pre-tessellation vertex shader
- Predicated rendering commands, conditions evaluated in hardware (culling operations, etc)
- Mixed OpenGL, CUDA, etc.

Higher Quality Rendering: VMD/Tachyon Ambient Occlusion Lighting

- Omnidirectional diffuse lighting
- Improved shape perception
- Tachyon tuned for use by VMD
- Tachyon AO lighting works with all VMD representations

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Interactive Display with AO and Other Demanding Techniques

- Ultimately the user wants to be able to display their structures at interactive rates
- Ambient occlusion lighting computationally costly:
 - Usable on very small static molecular structures, with some limitations
 - Published GPU algorithms don't scale well for large all-atom trajectories yet
 - Future GPUs and improved algorithms will likely make interactive AO usable for large structures in a few years

Upcoming Challenges

- Petascale simulations will generate trajectories too large to download from the supercomputers
- Much more analysis will have to be done prior to visualization of the results, to help focus on the interesting data

