Visualization and Analysis of Petascale Molecular Dynamics Simulations John E. Stone Theoretical and Computational Biophysics Group Beckman Institute for Advanced Science and Technology University of Illinois at Urbana-Champaign

http://www.ks.uiuc.edu/Research/gpu/

GPU Computing Symposium





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VMD – "Visual Molecular Dynamics"

- Visualization and analysis of:
 - molecular dynamics simulations
 - particle systems and whole cells
 - cryoEM densities, volumetric data
 - quantum chemistry calculations
 - sequence information
- User extensible w/ scripting and plugins
- http://www.ks.uiuc.edu/Research/vmd/





Whole Cell Simulation





MD Simulations



Sequence Data

Quantum Chemistry

VMD Interoperability Serves Many Communities

- Uniquely interoperable with a broad range of tools: AMBER, CHARMM, CPMD, DL_POLY, GAMESS, GROMACS, HOOMD, LAMMPS, NAMD, and many more ...
- Supports key data types, file formats, and databases, e.g. electron microscopy, quantum chemistry, MD trajectories, sequence alignments, super resolution light microscopy
- Incorporates tools for simulation preparation, visualization, and analysis





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GPU Computing

- Commodity devices, omnipresent in modern computers (over **one million** sold per **week**)
- Massively parallel hardware, thousands of processing units, **throughput oriented architecture**
- Standard integer and floating point types supported
- Programming tools allow software to be written in dialects of familiar C/C++ and integrated into legacy software
- GPU algorithms are often multicore friendly due to attention paid to **data locality** and **data-parallel** work decomposition



What Speedups Can GPUs Achieve?

- Single-GPU speedups of **3x** to **10x** vs. multi-core CPUs are common
- Best speedups can reach 25x or more, attained on codes dominated by floating point arithmetic, especially native GPU machine instructions, e.g. expf(), rsqrtf(), ...
- Amdahl's Law can prevent legacy codes from achieving peak speedups with shallow GPU acceleration efforts



CUDA GPU-Accelerated Trajectory Analysis and Visualization in VMD

VMD GPU-Accelerated Feature or Kernel	Typical speedup vs. multi-core CPU (e.g. 4-core CPU)
Molecular orbital display	30x
Radial distribution function	23x
Molecular surface display	15x
Electrostatic field calculation	11x
Ray tracing w/ shadows, AO lighting	8x
Ion placement	бх
MDFF density map synthesis	бх
Implicit ligand sampling	бх
Root mean squared fluctuation	бх
Radius of gyration	5x
Close contact determination	5x
Dipole moment calculation	4x







Peak Arithmetic Performance: Exponential Trend



Peak Memory Bandwidth: Linearish Trend

Theoretical GB/s



GPU Solution: Computing C₆₀ Molecular Orbitals

3-D orbital lattice:	Device	CPUs,	Runtime (s)	Speedup
millions of points				1 1
		GPUS		
	2x Intel X5550-SSE	8	4.13	1
	GeForce GTX 480	1	0.255	16
	GeForce GTX 480	4	0.081	51
Lattice slices computed on multiple GPUs	2-D CUDA grid on one GPU	CUDA the block	GPU each one iread	threads compute point.

Molecular Orbital Inner Loop, Hand-Coded x86 SSE Hard to Read, Isn't It? (And this is the "pretty" version!)

for (shell=0; shell < maxshell; shell++) {</pre>

__m128 Cgto = _mm_setzero_ps();

for (prim=0; prim<num_prim_per_shell[shell_counter]; prim++) {</pre>

float exponent = -basis_array[prim_counter];

float contract_coeff = basis_array[prim_counter + 1];

__m128 expval = _mm_mul_ps(_mm_load_ps1(&exponent), dist2);

__m128 ctmp = _mm_mul_ps(_mm_load_ps1(&contract_coeff), exp_ps(expval));

Cgto = _mm_add_ps(contracted_gto, ctmp); prim_counter += 2;

__m128 tshell = _mm_setzero_ps(); switch (shell_types[shell_counter]) {

case S_SHELL:

value = _mm_add_ps(value, _mm_mul_ps(_mm_load

case P_SHELL:

 $tshell = _mm_add_ps(tshell, _mm_mul_ps(_mm_load_ps1(\&wave_f[ifunc++]), xdist));$

tshell = _mm_add_ps(tshell, _mm_mul_ps(_mm_load_ps1(&wave_f[ifunc++]), ydist));

Writing SSE kernels for CPUs requires assembly language, compiler intrinsics, various libraries, **or** a really smart autovectorizing compiler **and lots of luck...**

break:

Molecular Orbital Inner Loop in CUDA

for (shell=0; shell < maxshell; shell++) {</pre>

```
float contracted_gto = 0.0f;
```

```
for (prim=0; prim<num_prim_per_shell[shell_counter]; prim++) {</pre>
```

```
float exponent = const_basis_array[prim_counter ];
float contract_coeff = const_basis_array[prim_counter + 1];
contracted_gto += contract_coeff * exp2f(-exponent*dist2);
prim_counter += 2;
```

```
}
```

float tmpshell=0;

```
switch (const_shell_symmetry[shell_counter]) {
```

```
case S_SHELL:
```

```
value += const_wave_f[ifunc++] * contracted_gto; break;
case P_SHELL:
```

```
tmpshell += const_wave_f[ifunc++] * xdist;
tmpshell += const_wave_f[ifunc++] * ydist
```

```
tmpshell += const_wave_f[ifunc++] * zdist;
```

value += tmpshell * contracted_gto; break;



Aaaaahhhh....

Data-parallel CUDA kernel looks like normal C code for the most part....

NAMD Titan XK7 Performance August 2013

NAMD on Titan Cray XK7 (2fs timestep with PME)



VMD Supports Petascale Biology

- Where to put the data?
 - o Trajectories too large to download
 - Analyze 231 TB trajectory set in 15 min, parallel I/O @ 275 GB/sec on 8,192 nodes
- Supports GPU-accelerated Cray XK7 nodes for both visualization and analysis tasks
 - GPU electrostatics, RDF, density quality-of-fit
 - OpenGL Pbuffer off-screen rendering support
 - GPU ray tracing w/ ambient occlusion lighting
- VMD analysis calculations and movie renderings use dynamic load balancing, tested with up to 262,144 CPU cores
- Available on: NCSA Blue Waters, ORNL Titan, Indiana Big Red II



NCSA Blue Waters Cray XE6 / XK7 Supercomputer 22,640 XE6 CPU nodes 4,224 XK7 nodes w/ GPUs enable fast

VMD analysis and visualization

VMD for Demanding Analysis Tasks Parallel VMD Analysis w/ MPI

- Compute time-averaged electrostatic fields, MDFF quality-of-fit, etc.
- Parallel rendering, movie making
- User-defined parallel reduction operations, data types
- Parallel I/O on Blue Waters:
 - 109 GB/sec on 512 nodes
 - 275 GB/sec on 8,192 nodes
- Timeline per-residue SASA calc. achieves 800x speedup @ 1000 BW XE6 nodes
- Supports GPU-accelerated clusters and supercomputers



Analyze large, long simulations with TimeLine





TimeLine:

- graphing and analysis tool to **identify events** in an MD trajectory
- live 2D whole-trajectory plot linked to 3D structure
- user-extendable

TimeLine 2D plot

Rho hexameric helicase 3D structure

- Perform analysis faster
 - High-performance parallel trajectory analysis on supercomputers and clusters
 - Current development versions show up to **3500x speedup** on Blue Waters
- Analysis types: filtering, time series analysis, sorting (e.g. bond energies)
- Remote interactive analysis: data at supercomputer center; view in office

Parallel TimeLine Calc. for Per-Residue Solvent-Accessible Surface Area



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Time-Averaged Electrostatics Analysis on Energy-Efficient GPU Cluster

- **1.5 hour** job (CPUs) reduced to **3 min** (CPUs+GPU)
- Electrostatics of thousands of trajectory frames averaged
- Per-node power consumption on NCSA "AC" GPU cluster:
 - CPUs-only: 448 Watt-hours
 - CPUs+GPUs: 43 Watt-hours
- GPU Speedup: 25.5x
- Power efficiency gain: **10.5**x



Quantifying the Impact of GPUs on Performance and Energy Efficiency in HPC Clusters. J. Enos, C. Steffen, J. Fullop, M. Showerman, G. Shi, K. Esler, V. Kindratenko, J. Stone, J. Phillips. *The Work in Progress in Green Computing*, pp. 317-324, 2010.

Time-Averaged Electrostatics Analysis on NCSA Blue Waters

NCSA Blue Waters Node Type	Seconds per trajectory frame for one compute node
Cray XE6 Compute Node: 32 CPU cores (2xAMD 6200 CPUs)	9.33
Cray XK6 GPU-accelerated Compute Node: 16 CPU cores + NVIDIA X2090 (Fermi) GPU	2.25
Speedup for GPU XK6 nodes vs. CPU XE6 nodes	XK6 nodes are 4.15x faster overall
Tests on XK7 nodes indicate MSM is CPU-bound with the Kepler K20X GPU. Performance is not much faster (yet) than Fermi X2090 Need to move spatial hashing, prolongation, interpolation onto the GPU	In progress XK7 nodes 4.3x faster overall

Preliminary performance for VMD time-averaged electrostatics w/ Multilevel Summation Method on the NCSA Blue Waters Early Science System

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Multilevel summation of electrostatic potentials using graphics processing units. D. Hardy, J. Stone, K. Schulten. *J. Parallel Computing*, 35:164-177, 2009.



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VMD "QuickSurf" Representation

- Displays continuum of structural detail:
 - All-atom models
 - Coarse-grained models
 - Cellular scale models
 - Multi-scale models: All-atom + CG, Brownian + Whole Cell
 - Smoothly variable between full detail, and reduced resolution representations of very large complexes
- GPU acceleration yields 10x-15x speedup vs. multi-core CPUs

Fast Visualization of Gaussian Density Surfaces for Molecular Dynamics and Particle System Trajectories. M. Krone, J. E. Stone, T. Ertl, K. Schulten. *EuroVis Short Papers*, pp. 67-71, 2012



Ray Tracing of VMD Molecular Graphics

- Ambient occlusion lighting, shadows, reflections, transparency, and much more...
- Satellite tobacco mosaic virus capsid w/ ~75K atoms





Standard OpenGL rasterization

VMD/Tachyon/CUDA/OptiX GPU ray tracing w/ ambient occlusion lighting

BW VMD/Tachyon Movie Generation



20 M atom chromatophore patch

360 XE6 nodes for 3h50m @ 4096x2400

HIV-1 Parallel Movie Rendering Results

- Unexpected I/O overhead from sourcing scripts!
- XK7 CUDA algorithms reduce per-frame surface and other geometry calculation times by a factor of ~15 vs. multithreaded SSE CPU code on XE6 nodes
- OpenGL rasterization is so fast it is essentially "free" I/O time dominates OpenGL test cases currently... (XK7 partition had no I/O nodes)
- For CPU-only Tachyon, XE6 nodes render almost exactly 2x faster than XK7 nodes
- All test cases start to be penalized at >= 512 nodes due to increased I/O contention for common input files, reading of scripts, etc need broadcast scheme for this data

VMD Movie Rendering on Blue Waters

	Rendering Mode		Nodes	Wall Clock Execution Time			
Movie Resolution		Node Type		Script Loading	State Loading	Geometry and Rendering	Total
	OpenGL rasterization	XK7	16	2 s	152 s	99 s	253 s
		XK7	32	2 s	158 s	45 s	205 s
		XK7	64	2 s	167 s	20 s	189 s
		XK7	128	2 s	191 s	11 s	205 s
		VU7	256	6.0	244 -	5 4 ~	255 -
"DoworDoint"		XK7	512	7 s	302 s	2.5 s	312 s
1057×652	In-place Tachyon ray tracing w/ ambient occlusion (AO) lighting	XK7	256	4 s	225 s	918 s	1,147 s
689,164 pixels		XK7	512	9 s	292 s	532 s	834 s
		XE6	128	2 s	83 s	943 s	1,029 s
		XE6	256	4 s	125 s	560 s	692 s
		XE6	512	7 s	221 s	330 s	560 s
	Combined OpenGL rasterization	XK7	256	4 s	214 s	913 s	1,170 s
	and Tachyon ray tracing w/ AO	XK7	512	9 s	300 s	531 s	848 s
4K UltraHD	OpenGL rasterization	XK7	512	9 s	300 s	3.1 s	314 s
3840×2160 8,294,400 pixels	Combined OpenGL rasterization and Tachyon ray tracing w/ AO	XK7	512	9 s	295 s	5,828 s	6,133 s
No Image Output	Tesla K20X CUDA Geometry Calc.	XK7	512	7 s	188 s	1.5 s	197 s
	CPU Geometry Calc.	XE6	512	7 s	214 s	23 s	244 s

TABLE II. VMD PARALLEL MOVIE RENDERING PERFORMANCE TESTS.

Early Experiences Scaling VMD Molecular Visualization and Analysis Jobs on Blue Waters. J. E. Stone, B. Isralewitz, and K. Schulten. In proceedings, Extreme Scaling Workshop, 2013. (In press)

GPU Ray Tracing of HIV-1 on Blue Waters

- 64 million atom virus simulation
- 1079 movie frames
- Surface generation and ray tracing stages each use >= 75% of GPU memory
- Ambient occlusion lighting, shadows, transparency, antialiasing, depth cueing, 144 rays/pixel minimum





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HIV-1 Parallel HD Movie Rendering on Blue Waters Cray XE6/XK7

New "TachyonL-OptiX" on XK7 w/ K20 GPU vs. Tachyon on XE6 GPUs yield up to **eight times** geom+ray tracing speedup

Node Type and Count	Script Load Time	State Load Time	Geometry + Ray Tracing	Total Time
256 XE6 CPUs	7 s	160 s	1,374 s	1,541 s
512 XE6 CPUs	13 s	211 s	808 s	1,032 s
64 XK7 Tesla K20X GPUs	2 s	38 s	655 s	695 s
128 XK7 Tesla K20X GPUs	4 s	74 s	331 s	410 s
256 XK7 Tesla K20X GPUs	7 s	110 s	171 s	288 s

GPU-Accelerated Molecular Visualization on Petascale Supercomputing Platforms, UltraVis'13: Eighth Workshop on Ultrascale Visualization Proceedings, 2013. (In press)

Optimizing GPU Algorithms for Power Consumption

NVIDIA "Carma" and "Kayla" single board computers

Tegra+GPU energy efficiency testbed

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- Quantifying the Impact of GPUs on Performance and Energy Efficiency in HPC Clusters. J. Enos, C. Steffen, J. Fullop, M. Showerman, G. Shi, K. Esler, V. Kindratenko, J. Stone, J Phillips. *International Conference on Green Computing*, pp. 317-324, 2010.
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